

User's Manual

Laser Bar Code Reader

BL-600 Series



Safety Precautions

This instruction manual describes the operation and function of the BL-600. Read this manual carefully to ensure safe use and maximum performance from your BL-600. The BL-600 Series uses a semiconductor laser as light source. Before using the product, see "Laser Safety Precautions" on page 1 to learn the safe and correct method of using the BL-600 Series.

Symbols

The following symbols alert you to important messages. Be sure to read these messages carefully.



Failure to follow instruction may lead to injury. (electric shock, burn, etc.)



Failure to follow instructions may lead to product damage.

Note: Provides additional information on proper operation.

Reference: Provides reference information about the operation.

General Precautions

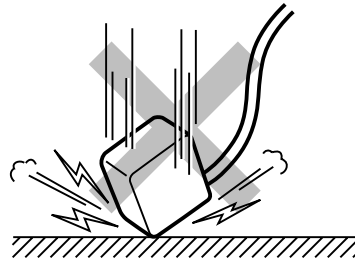
- At startup and during operation, be sure to monitor the functions and performance of the BL-600.
- We recommend that you take substantial safety measures to avoid any damage in the event a problem occurs.
- Do not open or modify the BL-600 or use it in any way other than described in the specifications.
- When the BL-600 is used in combination with other instruments, functions and performance may be degraded, depending on operating conditions and the surrounding environment.
- Do not use the BL-600 for the purpose of protecting the human body.

Warnings and Cautions Specific to the BL-600

CAUTION

- The BL-600 uses a 5 V DC power supply. Using a different voltage level may damage the unit.
When using the KEYENCE power supply unit BL-U1, BL-U2, N-42 or N-48, select the voltage level which can be supplied by the power supply unit. If a nonconforming power supply is connected, the BL-600 may be damaged.
- Before connecting or disconnecting the cable, be sure to turn off any device connected to the BL-600 Series. Otherwise, the BL-600 Series may be damaged.
- Do not disassemble or modify the BL-600 Series, as this may cause product failure.
- Locate cables as far as possible from high-voltage lines and power lines. Otherwise, generated noise may cause product failure or malfunctions.
- The BL-600 is a precision instrument. If the unit is dropped or shocked, it may be damaged. Take due consideration when transporting or installing the unit.

Incorrect



- Do not hold the cables when carrying the units. The units may hit each other and become damaged.

Incorrect



Environments and conditions for use



CAUTION

To use the BL-600 Series properly and safely, do not install it in locations with the following conditions. Use of the BL-600 Series in improper environments may cause fire, electric shock, product failure, damage, or malfunction.

- Locations where the BL-600 Series is exposed to direct sunlight
- Locations where the ambient temperature drops below 0°C or exceeds 45°C
- Locations where the relative humidity drops below 35% or exceeds 85%
- Locations where condensation occurs due to a sudden change in temperature
- Locations where a corrosive or flammable gas exists
- Locations exposed to dust, salt, metal particles, or greasy fumes
- Locations where the ambient light exceeds the range defined in the specifications
- Locations where the BL-600 Series is directly subjected to vibration or impact
- Locations where water, oil, or chemicals may splash the BL-600 Series
- Locations where a strong magnetic or electric field is generated

If abnormal conditions are encountered



CAUTION

If the following conditions are encountered, turn off the special power supply unit immediately. Continuing to use the BL-600 Series under abnormal conditions may cause fire, electric shock, or product failure.

Contact your nearest KEYENCE sales office or distributor (listed at the end of this manual) for repairs.

- Water or foreign matter enters the BL-600 Series
- The BL-600 Series is dropped or the housing is damaged.
- The BL-600 Series produces smoke or an abnormal smell

Note 1: You cannot perform any operation for 5 seconds after turning ON the BL-600. During this time, the motor rotation stabilizes. Wait for a while after turning ON the BL-600, then start reading or another operation.

Note 2: The BL-600 Series has a housing rated as IP-65 (except for the special power supply unit). It is not affected if water splashes it; however, a proper reading may not be ensured if the transmitter/receiver is dirty (fingerprints, water, oil, or dust). In such cases, wipe the dirt off with a soft cloth moistened with alcohol.

How this manual is organized

Chapter 1

Laser Safety Precautions

Chapter 2

Overview

This chapter describes the package contents, basic system configuration, and operation flow.

Chapter 3

Connection and Wiring

This chapter describes the connections and wiring between the BL-600 Series, special power supply unit, and peripheral devices.

Chapter 4

Setup Software

This chapter describes the usage of the setup software to set or perform reading tests of the BL-600.

Chapter 5

Installation

This chapter describes the procedure and cautions for the installation of the BL-600 Series and special power supply unit.

Chapter 6

Reading Operation and Other Functions

This chapter describes the reading operation and other functions, such as test mode, of the BL-600 Series.

Chapter 7

Serial Communication

This chapter describes the serial communication control.

Chapter 8

PLC Link

This chapter describes the PLC link control.

Appendices

The appendix includes specifications, reading characteristics, dimensions, troubleshooting, and index.

Warranties

1

2

3

4

5

6

7

8

Appendices

Warranties

Contents

Chapter 1

Laser Safety Precautions

1.1	Classification	2
1.2	Warning Labels	2
1.3	Labels Location	3
1.4	Safety Consideration	4
1.5	Safety Features Provided with the BL-600 Series	4

Chapter 2

Overview

2.1	Package Contents List and the BL Series Lineup	6
2.2	Part names and functions	8
2.3	System Configuration and Connection/Operation Procedures	12
2.3.1	Basic system configuration and connection/ operation procedures for RS-232C communication	12
2.3.2	Basic system configuration and connection/ operation procedures for RS-422A communication	13
2.3.3	Multi-drop link communication (RS-485)	14

Chapter 3

Connection and Installation

3.1	Connecting BL-U1 and Wiring	16
3.1.1	Connecting the BL-U1, AC power supply, and BL-600 Series	16
3.1.2	DIP switch setting	17
3.1.3	Terminals of I/O terminal block and wiring	18
3.1.4	Connecting RS-232C	20
3.1.5	Wiring the RS-422A	23
3.2	Connecting the BL-U2/N-42 and Wiring	25
3.2.1	Connecting the BL-U2/N-42, AC power supply, and BL-600 Series	25
3.2.2	Terminals of I/O terminal block and connections	26
3.2.3	Connecting RS-232C (BL-U2)	28
3.2.4	Connecting the N-42 to RS-422A	31
3.3	Wiring without the Special Power Supply Units	33
3.3.1	Pin assignments of the BL-600 Series connector and the connecting power supply	33
3.3.2	I/O Wiring	34
3.3.3	RS-232C connection	35

Chapter 4

Setup Software

4.1	Installing and Operating the Setup Software	38
4.1.1	Installation and operation procedures	38
4.1.2	Installing setup software	39
4.1.3	Installation/Start-up	39

4.1.4	Initial screen	40
4.1.5	Basic operation	41
4.2	Setup Procedure	42
4.2.1	Model selection	42
4.2.2	[[Main]] (Operation setting) screen	42
4.2.3	[[Comm Settings-1]] (Communication parameters 1) screen	45
4.2.4	[[Comm Settings-2]] (Communication parameters 2) screen	46
4.2.5	[[Code setup]] (Bar code setting) screen	49
4.2.6	[[Utility]] screen	53
4.3	Sending/Receiving Settings	54
4.3.1	Sending/receiving settings to/from the BL-600 Series	54
4.3.2	Sending/receiving settings to/from the BL-600 Series via the N-400	57
4.4	Reading/Saving/Printing File	59
4.4.1	[[Files]] screen	59
4.4.2	Reading a previously saved setting file	59
4.4.3	Saving updated settings in a file	60
4.4.4	Comparing the contents of the file currently being edited with a saved file	61
4.4.5	Printing contents of a setting file	61
4.4.6	Resetting the edited settings to the initial (factory) settings	62
4.5	Using Monitor	62
4.5.1	Receiving data and checking the result	62
4.5.2	Command transmission	63
4.5.3	Starting the test mode	65
3.5.4	Changing the scanning width	66
4.6	List of Error Messages	67
4.7	Example of printing from the setup software	68

Chapter 5

Installation

5.1	Installation of the BL-600 Series	72
5.1.1	Situations to check for before installing the BL-600 Series	72
5.1.2	Mounting angle and distance	74
5.1.3	Mounting the BL-600/601/600HA/601HA	75
5.1.4	Mounting the BL-650HA/651HA	77
5.1.5	Mounting the BL-600 Series without the mounting bracket	79
5.2	Installation of the Special Power Supply Unit	81
5.2.1	In-panel installation	81
5.2.2	Installing the BL-U1	81
5.2.2	Installing the BL-U2 and N-42	83

Chapter 6

Functions for Reading Operation

6.1	Read Operation	86
6.1.1	Scanning method	86
6.2	Read Modes	88
6.2.1	Single label read mode	88

6.2.2	Multi-label read mode 1 (Multi 1)	89
6.2.3	Multi-label read mode 2 (Multi 2)	90
6.2.4	Multi-label read mode 3 (Multi 3)	91
6.3	Label Orientation Mode	93
6.4	Test Mode	94
6.4.1	Reading rate check mode	94
6.4.2	Tact check mode	97
6.4.3	Online test mode	99
6.5	Preset Function (Compare with:)	101
6.5.1	Preset function	101
6.5.2	Using “?” and “!” in the preset data	101
6.6	Additional information function	102
6.6.1	Decode match count add function	102
6.6.2	Scan count add function (valid only if using the decoding count add function)	102
6.6.3	Code type add function	103
6.6.4	Label orientation add function	103
6.6.5	Symbology ID add function	104
6.6.6	PMI add function	104
6.6.7	Order of the additional information	106
6.7	Max. Code Length (Designated Digit) Output Function	107

Chapter 7

Serial Communication

7.1	Serial Communication	110
7.2	Details on Data Communication	111
7.3	Command Communication	114
7.3.1	Setup of direct control commands	114
7.3.2	Details on parameter setting commands	118

Chapter 8

PLC Link

8.1	PLC Link	130
8.1.1	List of PLCs used for PLC link	130
8.1.2	Devices used for PLC link	131
8.2	Setting the BL-600 and PLC	132
8.2.1	Setting the BL-600 Series	132
8.2.2	Setting the PLC	132
8.3	Device Assignment	135
8.3.1	Data memory head address	135
8.3.2	Data memory areas	136
8.3.3	Detailed description of device assignment	137
8.4	PLC Link Error	142
8.5	Communication Time	143

Appendices

Appendix A BL-600 Series Specifications	146
Appendix A.1 Specifications	146
Appendix A.2 Reading Range Characteristics (Typical)	148
Appendix A.3 Angular Characteristics (Typical)	151
Appendix B BL-U1 Specifications	152
Appendix C BL-U2, N-42 Specifications	153
Appendix D Dimensions	154
Appendix E Sample Program for the PLC Link	159
Appendix F Troubleshooting	162
Appendix F.1 Bar codes cannot be read	162
Appendix F.2 Reading rate check mode is not 100%	163
Appendix F.3 The setting data cannot be sent/ received using the setup software	163
Appendix F.4 Cannot communicate successfully when using the PLC link	163
Appendix G CODE93 Specifications	164
Appendix H CODE128 Specifications	165
Appendix I Checksum Calculation Method	167
Appendix J ASCII Code Table	169
Appendix K Setup Parameter List	170
Appendix L Default Setting List	173

Warranties

WARRANTIES AND DISCLAIMERS	181
---	-----



Chapter 1

Laser Safety Precautions

1.1	Classification	2
1.2	Warning Labels	2
1.3	Label Location	3
1.4	Safety Consideration	4
1.5	Safety Features Provided with the BL-600 Series	4

1.1 Classification

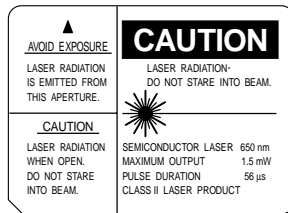
Model	BL-600/601/600HA/601HA	BL-650HA/651HA
FDA	Class II	
IEC 825-1 11.1993	Class 2	
DIN EN 60825-1 07.1994	Klasse 2	

1.2 Warning Labels

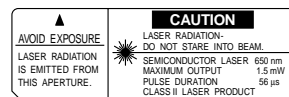
1) Warning labels

■ FDA

BL-600/601/600HA/601HA

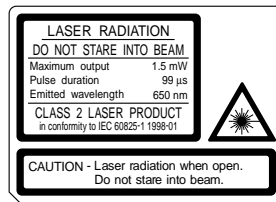


BL-650HA/651HA

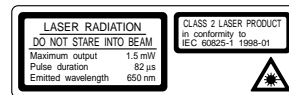


■ IEC

BL-600/601/600HA/601HA



BL-650HA/651HA



■ DIN

BL-600/601/600HA/601HA

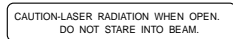


BL-650HA/651HA

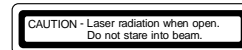


2) Protective housing label

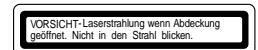
■ FDA



■ IEC



■ DIN

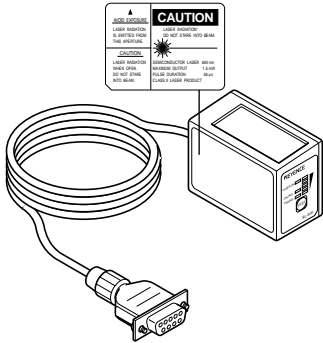


1.3 Labels Location

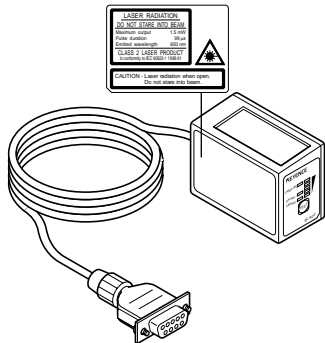
FDA Warning labels are attached to the sensor head as shown below. The IEC/DIN Warning labels are packaged with the BL-600 series. Affix the Warning labels on the sensor head as shown below.

■ BL-600/601/600HA/601HA

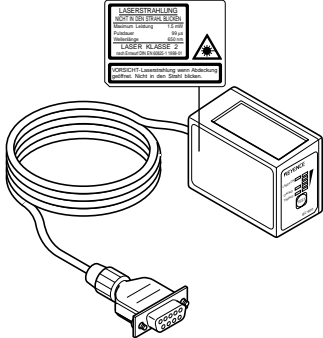
FDA



IEC

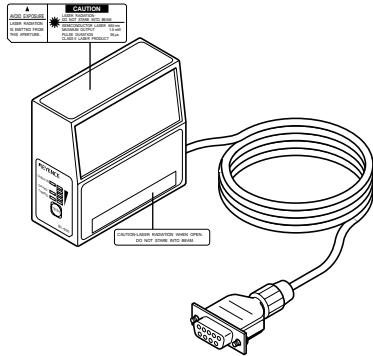


DIN

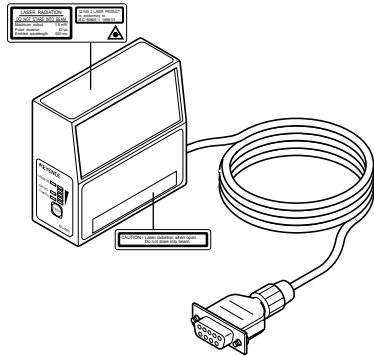


■ BL-650HA/651HA

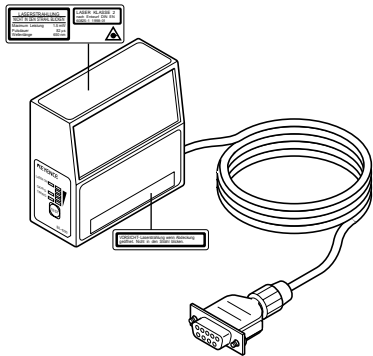
FDA



IEC



DIN



1.4 Safety Consideration



CAUTION

Use of controls or adjustment, or the performance of procedures other than those specified herein, may result in hazardous radiation exposure.

The laser beam is not harmful to the skin. There is, therefore, no danger in exposing arms or hands to the beam. The only possible health hazard is in exposing the eyes to the laser beam. Damage to the eyes can occur if the operator stares directly into the beam.



WARNING

Follow the safety precautions below to ensure operator safety:

- **Operate the BL-600 Series only according to the procedures described in this instruction manual.**
Otherwise, injury may occur due to exposure to the laser beam.
- **Do not disassemble the sensor head.**
Laser emission from the BL-600 series is not automatically stopped if the sensor head is disassembled. If you disassemble the sensor head for inspection or repair, you may be exposed to the laser beam. If the BL-600 series malfunctions, contact KEYENCE immediately.
- **Do not look directly at the laser beam.**
Looking directly at the laser beam may result in serious eye injury.
- **Protective enclosure**
We recommend that you install a protective enclosure around the sensor head to prevent any person from getting near the sensor head during operation.
- **Protective goggles**
We recommend that you wear protective goggles when using the BL-600 series.
- **Stop laser emissions before cleaning the laser emission port.**
Failure to stop the laser emission may expose eyes to the laser beam.
- **Check the laser beam path.**
To prevent exposure to the laser beam due to specular or diffuse reflection, install a screen which offers the appropriate reflectance and temperature characteristics to interrupt the reflected laser beam. Do not install the BL-600 series in such a way that the laser beam passes at eye height.

1.5 Safety Features Provided with the BL-600 Series

The BL-600 series is provided with the following safety features. Make sure these features function correctly before operating.

- **Laser emission caution LED (LASER ON LED)**
During laser emission, the LASER ON LED illuminates. The LED ON status can be checked through the laser protective glasses.
- **Laser forced OFF command**
Sending the laser forced OFF command (LOCK, see page 116) to the BL-600 can inhibit emission of laser beams. When working near the laser transmitter, be sure to use the laser forced OFF command to avoid looking into the laser beams.

When this command is selected, the bottom STABILITY LED flashes.

Chapter 2

Overview

This chapter describes the package contents, basic system configuration, and operation flow.

2.1	Package Contents List and the BL Series Lineup	6
2.2	Part Names and Functions	8
2.3	System Configuration and Connection/ Operation Procedures	12
2.3.1	Basic system configuration and connection/operation procedures for RS-232C communication	12
2.3.2	Basic system configuration and connection/operation procedures for RS-422A communication	13
2.3.3	Multi-drop link communication (RS-485)	14

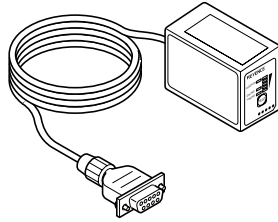
2.1 Package Contents List and the BL Series Lineup

The packages of the BL-600 Series, optional power supply unit, and setup software contain the following components. Be sure to check that you have all the package contents before use.

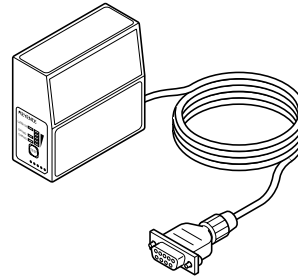
Laser bar code reader

BL-600 Series (BL-600/601/600HA/601HA/650HA/651HA)

Laser bar code reader: 1
BL-600/601/600HA/601HA



BL-650HA/651HA



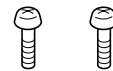
Insulating spacer: 4



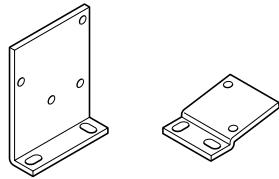
Washer: 4



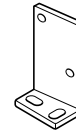
Mounting screw (M3): 2



BL-600/601/600HA/601HA
Mounting bracket
A and B: 1 each



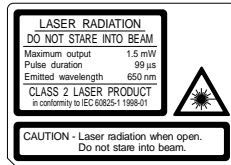
BL-650HA/651HA
Mounting bracket : 1



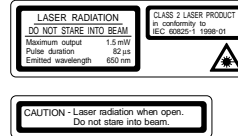
Instruction manual: 1



Laser warning label (Japanese/English/German/French): 1
BL-600/601/600HA/601HA



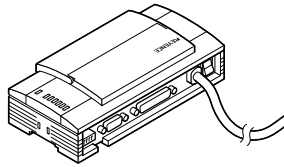
BL-650HA/651HA



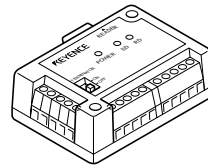
Model	Reading direction	Scanning method	Readable bar width	Reading distance
BL-600	Front	Single	0.19 to 1.0 mm	75 to 330 mm (When narrow width is 1.0 mm)
BL-601		Raster		
BL-600HA		Single	0.125 to 1.0 mm	35 to 190 mm (When narrow width is 0.5 mm)
BL-601HA		Raster		
BL-650HA	Side	Single	0.125 to 1.0 mm	45 to 175 mm (When narrow width is 0.5 mm)
BL-651HA		Raster		

Power supply (Option)

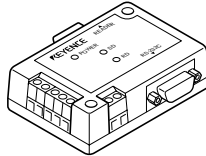
■ BL-U1



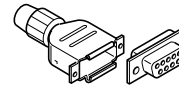
■ N-42/N-48



■ BL-U2



D-sub 9-pin connector,
connector case: 1 each

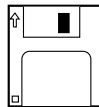


Model	Supply voltage	Interface
BL-U1	100 to 240 V AC	RS-232C, RS-422A, or RS-485 (multi-drop link) (Select one of these)
BL-U2	24 V DC	RS-232C
N-42	24 V DC	RS-422A
N-48	24 V DC	RS-485(multi-drop link)

Setup software (Option)

■ BL-H60WE

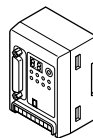
Setup software
3.5-inch floppy disk: 1



Other options

■ N-400: Multi-drop controller

Used as the master unit when multi-drop linking with the BL Series.



The package contents have been carefully inspected; however, if any component should be defective or damaged, contact your nearest KEYENCE office or distributor (listed at the end of this manual).

■ OP-27937: RS-232C Null modem cable (D-sub 9-pin)

Used for connecting BL-600 reader to optional power supply units BL-U2.

■ OP-22149: RS-232C Null modem cable

Used for connecting BL-600 reader to optional power supply units BL-U1.

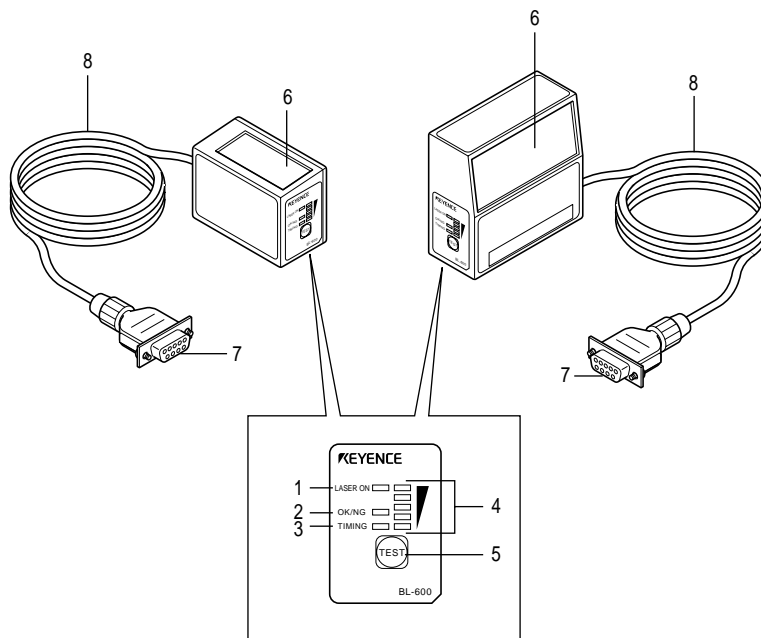
■ OP-25057: 25-to 9-pin adaptor

2.2 Part Names and Functions

This section describes the part names and functions of the BL-600 Series and special power supply unit.

■ BL-600/601/600HA/601HA

■ BL-650HA/651HA

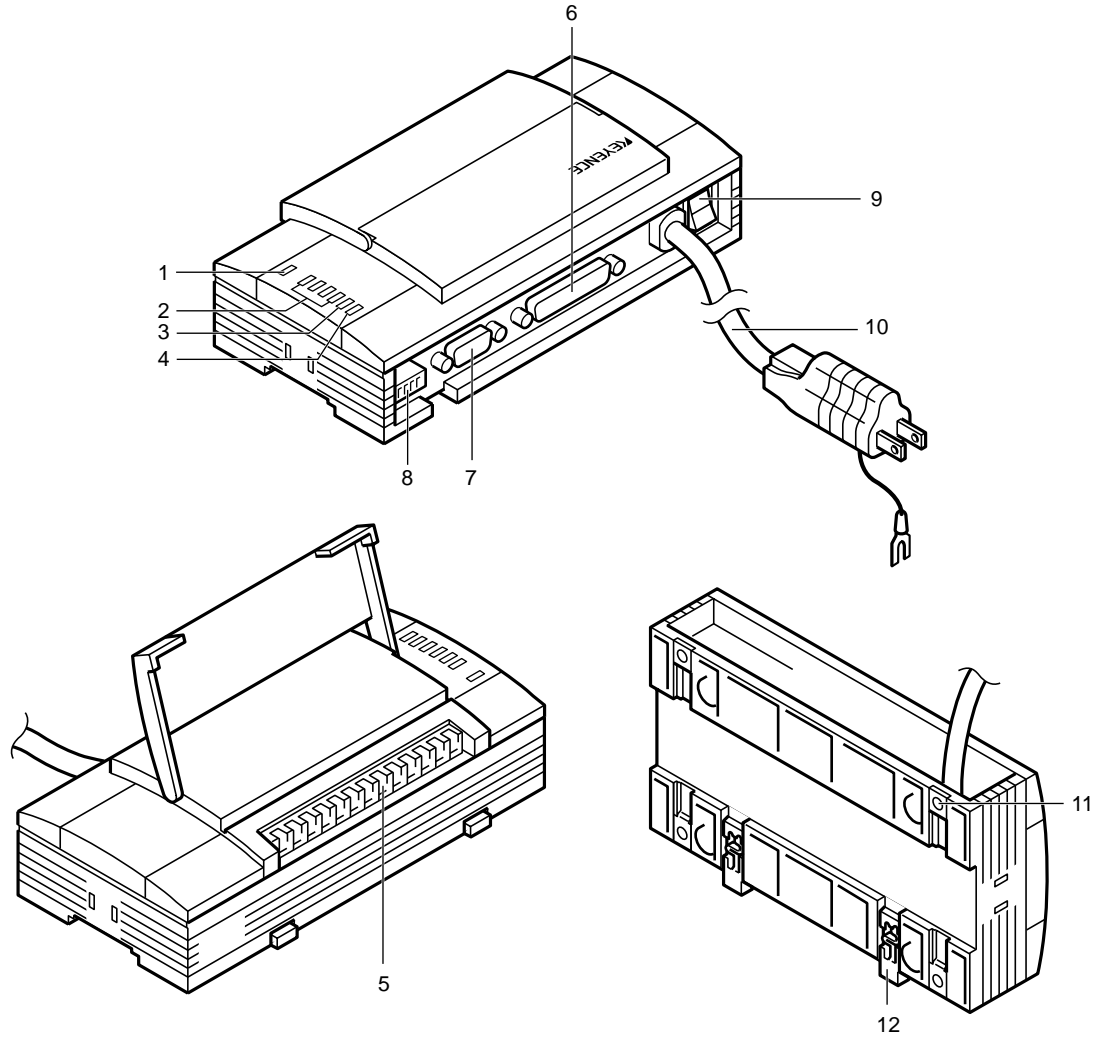


No.	Name	Function
1	LASER ON LED	Lit when laser beams are emitted.
2	OK/NG LED	<ul style="list-style-type: none"> When OK output is ON: The green LED lights. When NG output is ON: The red LED lights.
3	TIMING LED	Lit when trigger input is ON.
4	STABILITY LED	Displays the reading stability (⇒ See pages 95, 98, 100.) and the BL-600 operating status. (⇒ See the table on the next page.)
5	TEST SWITCH	This switch allows the following operations: <ul style="list-style-type: none"> Start the text mode. Pressing the switch once within two minutes reads the bar code once. Sets the communication protocol to the intival values when sending the settings. (⇒ See page 54.) Reset the error status.
6	Transmitter/receiver	Window to emit laser beams and receive reflected lights.
7	Power supply connector	Connected to the special power supply unit.
8	Cable	Cable length is 1.9 m.

STABILITY LED display according to the operating status

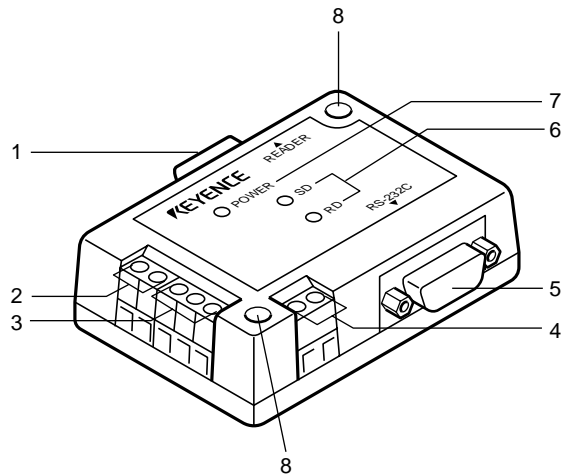
Operating status	STABILITY LED display	Action to be taken
Power-on	LEDs turn on sequentially starting from the bottom.	———
During setup ⇨ See pages 116, 118.	All the LEDs flash.	———
Waiting for setting data send/receive ⇨ See page 54.	The first, third, and fifth LEDs from the top flash simultaneously.	———
Laser forced OFF ⇨ When LOCK command is sent, see page 116.	The bottom LED flashes.	———
Unit error	Either of the second, third, or fourth LEDs from the top flashes.	The BL-600 Series may have failed or the supply voltage may have dropped. If the voltage is normal, the unit may have a problem. Contact your nearest KEYENCE office or distributor.
PLC link error ⇨ See page 142.	The top LED flashes.	Press the TEST switch to reset the error.

■ BL-U1



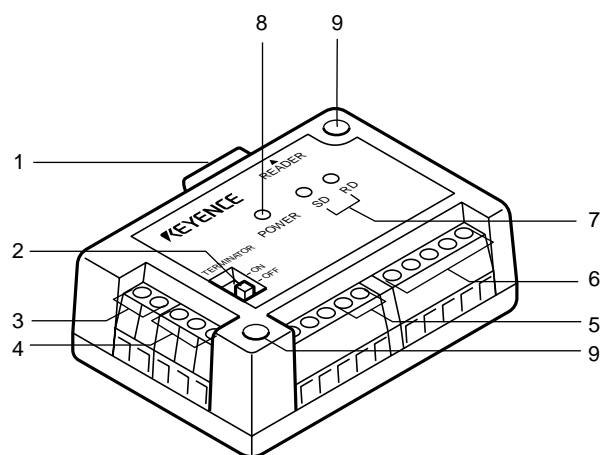
No.	Name	Function
1	POWER LED	Lit when power is ON.
2	Communication status indicator LEDs	<ul style="list-style-type: none"> Allows you to monitor the communication status of the RS-232C port. The SD, RD, RS and CS indicators are provided in this order from the top.
3	TIMING LED	Lit when trigger input is ON.
4	OK/NG LED	<ul style="list-style-type: none"> When OK output is ON: The green LED lights. When NG output is ON: The red LED lights.
5	I/O terminal block	Includes the trigger input terminal, OK/NG output terminals, and RS-422A/RS-485 (multi-drop link) connecting terminals.
6	RS-232C port	Used to connect to a personal computer. This port is unused when RS-485 (multi-drop link) is used.
7	READER port	Connect the BL-600 Series to this port.
8	DIP switches	Switches the communication port, and turns the terminator ON/OFF.
9	Power switch	Tuns the power ON/OFF.
10	Power supply cable	Use a 100 to 240 V AC (50/60 Hz) power supply. Cable lenght is 2 m.
11	Mounting bracket	Used when the BL-U1 is mounted with screws.
12	DIN-rail mounting claw	Used when the BL-U1 is mounted to a DIN rail.

■ BL-U2



No.	Name	Function
1	READER port	Connect to a BL-600 Series bar code reader.
2	TRIGGER input terminals	Connect to a photoelectric sensor for trigger input.
3	OK/NG output terminals	Output OK/NG signals.
4	Power supply terminals	Connect to a 24 V DC power supply.
5	RS-232C port	Connect to a personal computer, etc.
6	Communication status indicator LEDs	<ul style="list-style-type: none"> Indicate the communication status of the RS-232C. The SD and RD indicators are provided in this order from the top.
7	POWER LED	Light when the power is on.
8	Mounting hole	Used when the BL-U2 is mounted with screws.

■ N-42

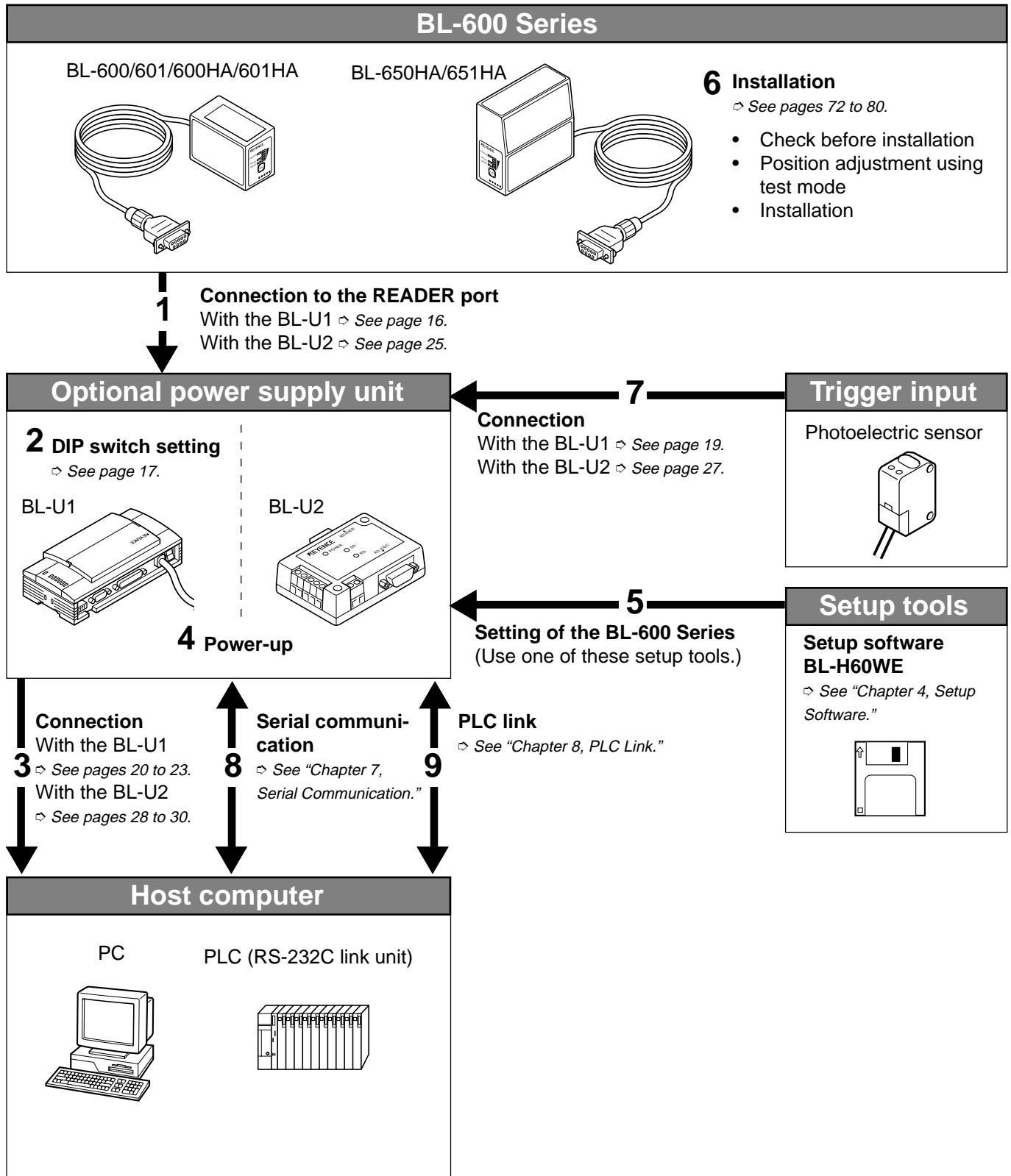


No.	Name	Function
1	READER port	Connect to a BL-600 Series bar code reader.
2	Terminator switch	Turns ON/OFF the terminator (Termination resistance: 100 Ω).
3	TRIGGER input terminals	Connect to a photoelectric sensor for trigger input.
4	OK/NG output terminals	Output OK/NG signals.
5	Power supply terminals	Connect to a 24 V DC power supply.
6	RS-422A terminals	Connect to an RS-422A device.
7	Communication status indicator LEDs	<ul style="list-style-type: none"> Indicates the communication status of the RS-422A. The SD and RD indicators are provided in this order from the left.
8	POWER LED	Light when the power is turned ON.
9	Mounting hole	Used when the N-42 is mounted with screws.

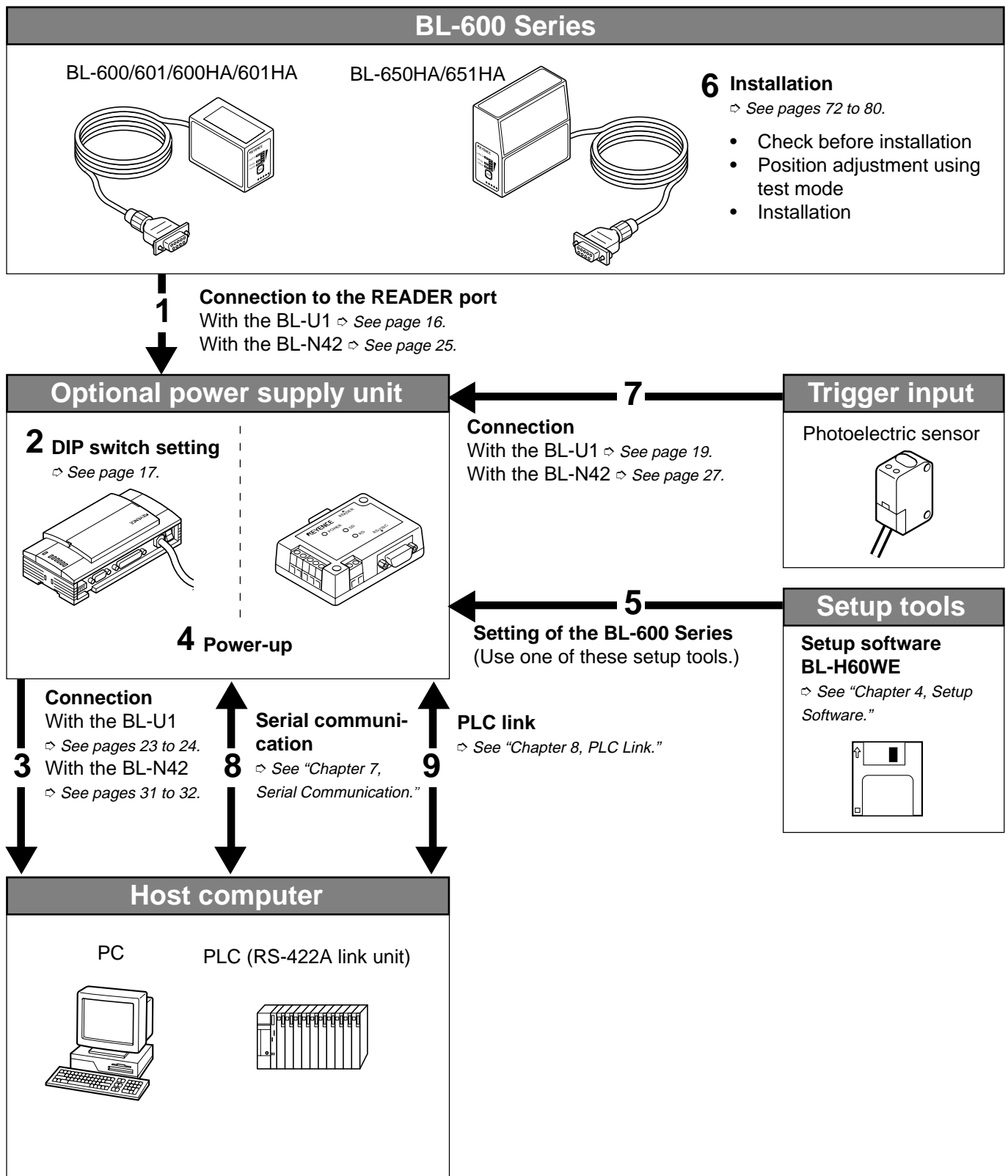
2.3 System Configuration and Connection/Operation Procedures

This section describes the basic system configuration and the connection/operation procedures to use RS-232C, RS-422A, or multi-drop link.

2.3.1 Basic system configuration and connection/operation procedures for RS-232C communication



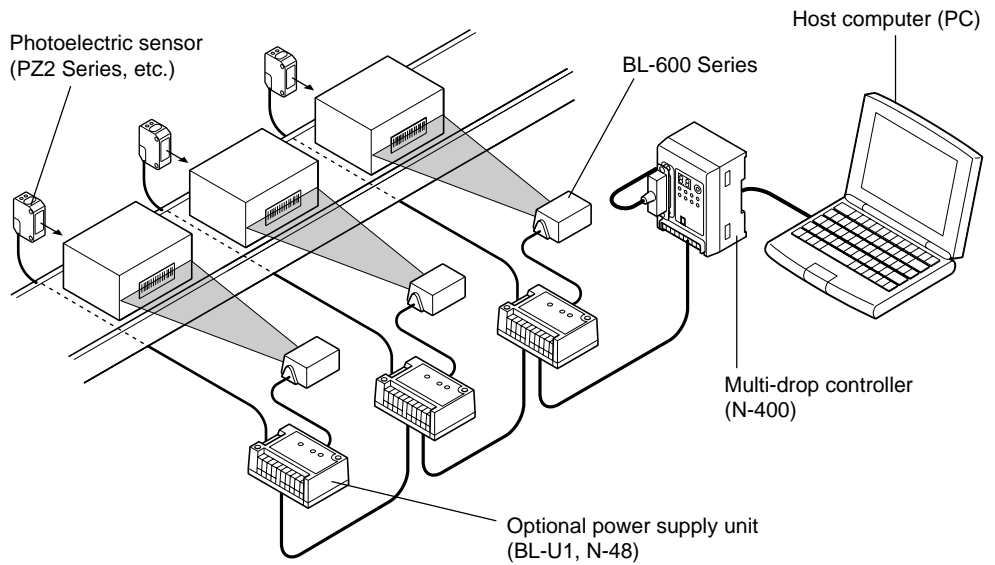
2.3.2 Basic system configuration and connection/operation procedures for RS-422A communication



Note: When the N-42 is used as a power supply unit, the communication type is set to RS-422A, therefore the BL-600 Series cannot be connected directly to a personal computer. To set the BL-600 Series with a personal computer, use an RS-232C type power supply unit (BL-U1 or BL-U2).

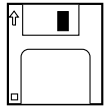
2.3.3 Multi-drop link communication (RS-485)

The following devices are required for the multi-drop link to control several BL-600 Series units with a host computer.



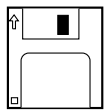
■ BL-600 Series setup tools

Setup software BL-H60WE



■ N-400 setup tools

Setup software (Provided with N-400)



⇒ Refer to the N-400 User's Manual for connection and usage of the multi-drop link.

Chapter 3

Connection and Installation

This chapter describes the connections and wiring between the BL-600 Series, special power supply unit, and peripheral devices.

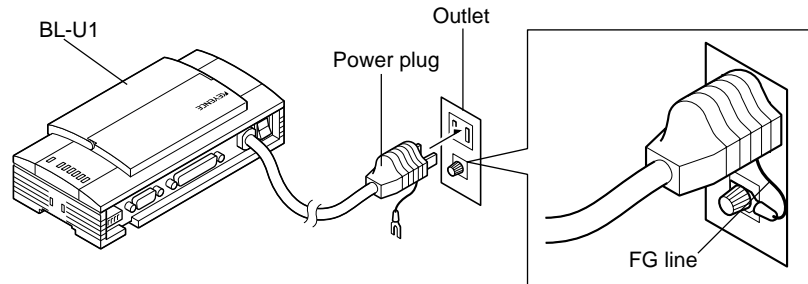
3.1	Connecting BL-U1 and Wiring	16
3.1.1	Connecting the BL-U1, AC power supply, and BL-600 Series	16
3.1.2	DIP switch setting	17
3.1.3	Terminals of I/O terminal block and wiring.....	18
3.1.4	Connecting RS-232C	20
3.1.5	Wiring the RS-422A	23
3.2	Connecting the BL-U2/N-42 and Wiring	25
3.2.1	Connecting the BL-U2/N-42, AC power supply, and BL-600 Series	25
3.2.2	Terminals of I/O terminal block and connections	26
3.2.3	Connecting RS-232C (BL-U2)	28
3.2.4	Connecting the N-42 to RS-422A	31
3.3	Wiring without the Special Power Supply Units	33
3.3.1	Pin assignments of the BL-600 Series connector and the connecting power supply	33
3.3.2	I/O Wiring	34
3.3.3	RS-232C connection	35

3.1 Connecting BL-U1 and Wiring

This section describes the connection and wiring of the BL-600 Series and peripheral devices when the special power supply unit BL-U1 is used.

3.1.1 Connecting the BL-U1, AC power supply, and BL-600 Series

1. Plug the BL-U1 power cable into an outlet.

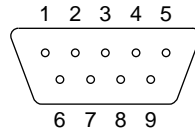


Do not use a power supply other than 100 to 240 V AC (50/60 Hz). An improper power supply may cause product failure.

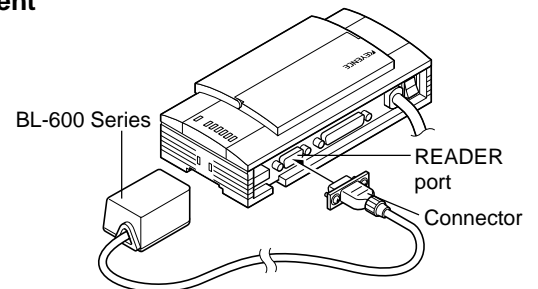
Note: If the noise conveyed through the FG line causes an LB-600 Series reading error, do not connect the FG line.

2. Connect the BL-600 Series to the READER port of the BL-U1.

■ BL-U1 READER port pin assignment



D-sub 9-pin (male)
DCE specification (defined as terminal)
#4-40 screw (female)



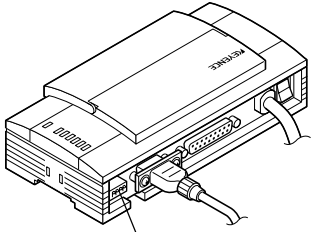
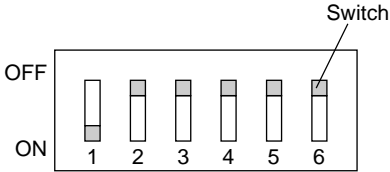
Pin No.	Symbol	Function	Signal direction
1	TIM	Trigger input	Output
2	RD (RXD)	Sends RS-232C data.	Output
3	SD (TXD)	Receives RS-232C data.	Input
4	OK	OK	Input
5	GND (SG)	Ground (Common ground for respective signal)	—
6	NG	NG	Input
7	RS (RTS)	Ready to send RS-232C data.	Input
8	CS (CTS)	Request to send RS-232C data. (Control method can be selected with the DIP switches.) ↪ See page 17.	Output
9	+5 V	+5 V power supply	Output

Note: Do not extend the power cable. A long power cable can cause a voltage drop, preventing the BL-600 from starting properly.

3.1.2 DIP switch setting

Change the DIP switch setting according to the type of communication and terminator setting.

■ **DIP switch**



* The figure above shows the factory-settings.

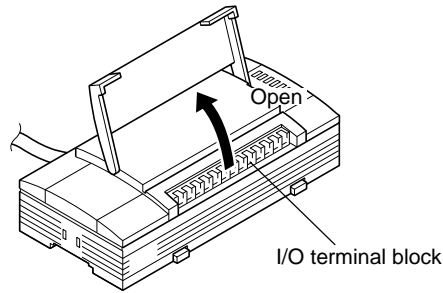
DIP switch

DIP Switch No.		1	2	3	4	5	6
Communication type selection	RS-232C (Factory-setting)	ON	OFF	OFF			
	RS-422A	OFF	ON	OFF			
	RS-485 (Multi-drop link)	OFF	OFF	ON			
RS-422A terminator (Termination resistance: 100 Ω)	OFF				OFF		
	ON				ON		
RS-485 terminator (Termination resistance: 100 Ω)	OFF					OFF	
	ON					ON	
Selection of READER port CS control method	ON or OFF according to the RS-232C port CS signal status.						OFF
	Normally ON						ON

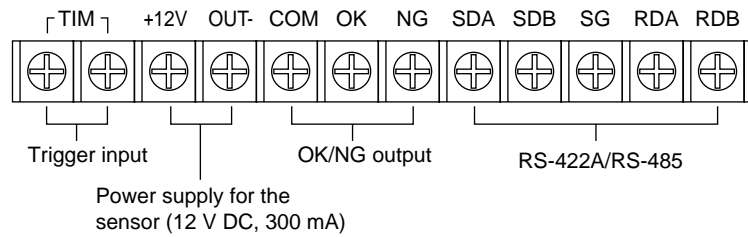
3.1.3 Terminals of I/O terminal block and wiring

Terminals of the I/O terminal block

The terminals of the I/O terminal block are assigned as shown in the figure.



Terminal assignment



Symbol	Description	Signal direction
TIM	Trigger input	Input
+12 V OUT-	+ terminal of power supply for sensor (12 V DC, 300 mA)	Output
	- terminal of power supply for sensor (0 V)	Output
COM	Common terminal for OK/NG output	—
OK	OK output	Output
NG	NG output	Output
SDA	+ terminal for RS-422A data transmission/RS-485 + terminal	Output, Input/Output
SDB	- terminal for RS-422A data transmission/RS-485 - terminal	Output, Input/Output
SG	Signal ground	—
RDA	+ terminal for RS-422A data reception	Input
RDB	- terminal for RS-422A data reception	Input

Applicable crimp terminals

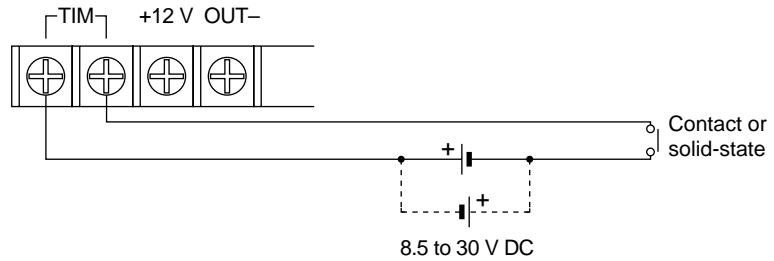
M3.0 screws are used for the terminal block.
Use the following crimp terminal for connection.

Shape of applicable crimp terminal

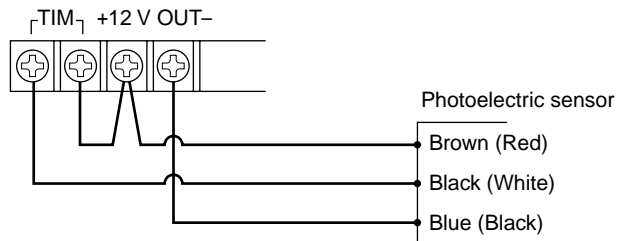


Connecting trigger input

The trigger input allows the BL-600 Series to start reading bar codes (turn on the laser beam).
 The trigger input is turned ON when 8.5 to 30 V DC input is activated between the trigger input terminals.
 The BL-U1's power supply terminals for the sensor can be used as the power supply input for the sensor.

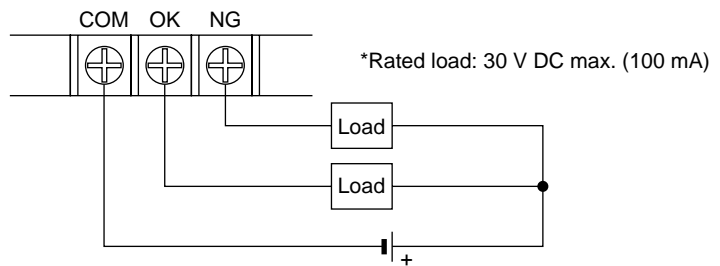


■ Connection to a photoelectric sensor manufactured by KEYENCE

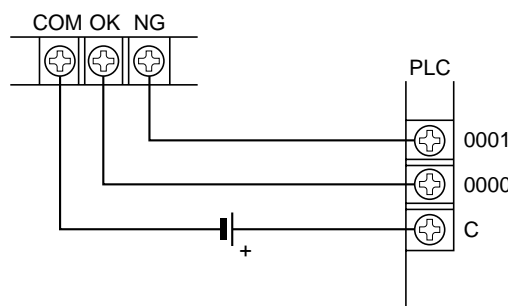


Connecting the OK/NG output

The OK/NG output is used to differentiate between acceptable and unacceptable results based on a comparison with preset data (↔ See pages 101.). It can also be used to indicate whether or not the BL-600 Series successfully reads bar codes when there is no preset data entered.
 The OK/NG output is an NPN open-collector output.

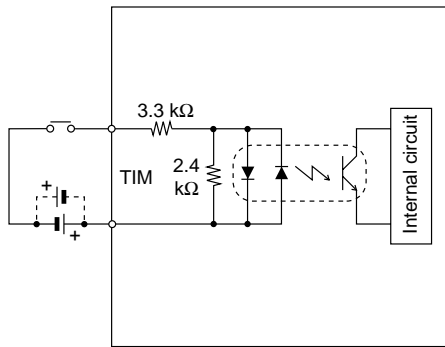


■ Connection to a programmable logic controller (PLC) manufactured by KEYENCE

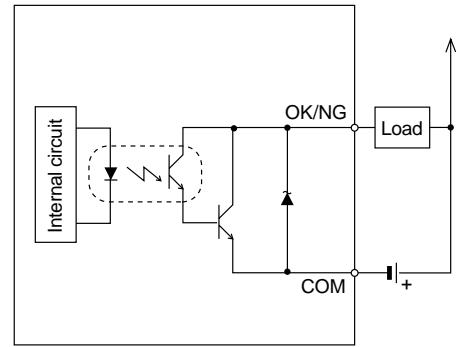


I/O circuit diagram

■ Input circuit diagram



■ Output circuit diagram



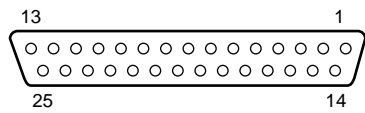
3

3.1.4 Connecting RS-232C

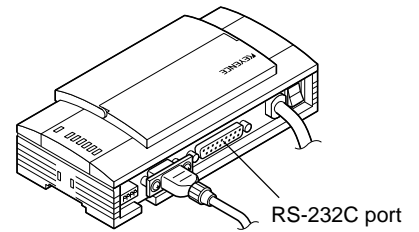
Pin assignment of the RS-232C port

The BL-U1 has a RS-232C port with the following pin assignment.

■ RS-232C port pin assignment



D-sub 25-pin (female)
DTE specification (defined as terminal)
M2.6 screw (female)



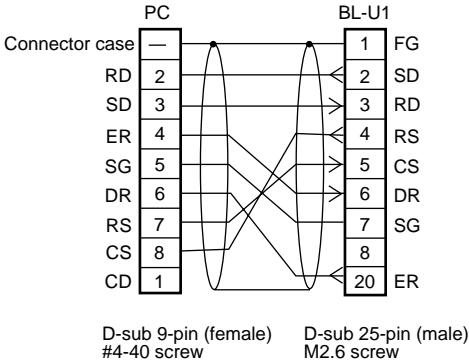
Pin No.	Symbol	Function	Signal direction
1	FG	Frame ground	—
2	SD (TXD)	Sends RS-232C data	Output
3	RD (RXD)	Receives RS-232C data	Input
4	RS (RTS)	Request to send RS-232C data (always ON)	Output
5	CS (CTS)	Ready to send RS-232C data	Input
6	DR (DSR)	Connected to pin No. 20 inside.	Input
7	GND (SG)	Signal ground	—
20	ER (DTR)	Connected to pin No. 6 inside.	Output

Wiring the RS-232C cable

Connect the BL-U1 to a personal computer or other devices with the following wiring.

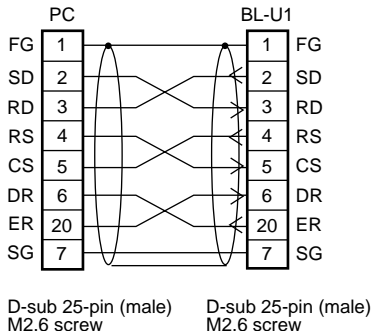
■ Connecting a PC

9-pin serial port



* KEYENCE option OP-22149 (1.5 m) and OP-25057 (conversion connector) can be used.

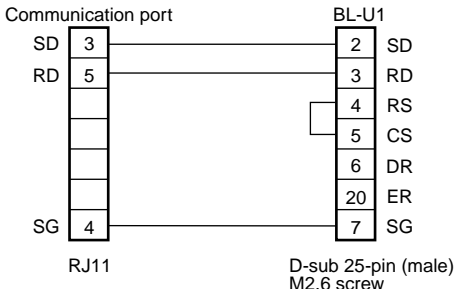
25-pin serial port



* KEYENCE option OP-22149 (1.5 m) or commercially available cross cable can be used.

■ Connecting NEW KV Series/Communication port

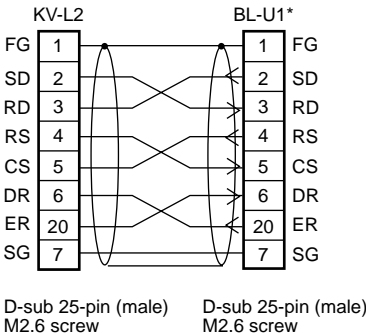
KV-10/16/24/40



* KEYENCE option OP-96368 (2.5 m) and OP-96369 (conversion connector) can be used.

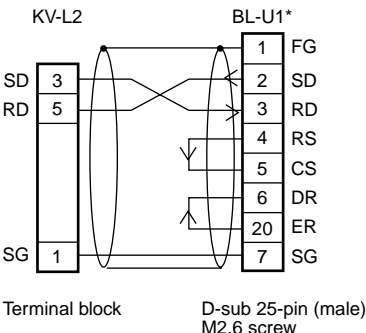
■ Connecting KV-L2*

Port 1



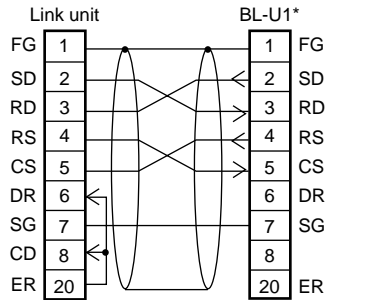
* KEYENCE option OP-22149 (1.5 m) or commercially available cross cable can be used.

Port 2



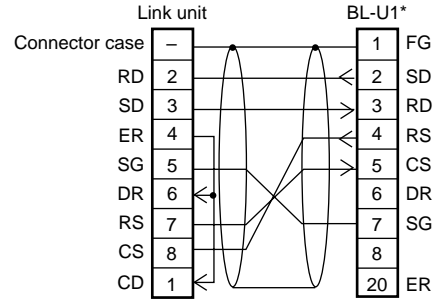
■ Connecting MELSEC-A Series

Connection with AJ71(U)C24(-S□),
AJ71QC24-R2,
A0J2-C214-S1



D-sub 25-pin (male) M2.6 screw D-sub 25-pin (male) M2.6 screw

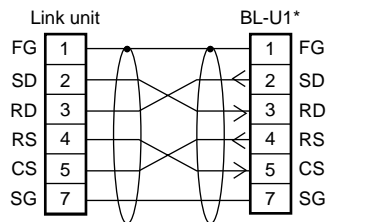
Connection with A1SJ71(U)C24-R2/PRF,
A2CCPUC24(-PRF)



D-sub 9-pin (male) M2.6 screw D-sub 25-pin (male) M2.6 screw

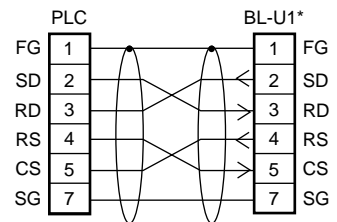
■ SYSMAC-C Series

Connection with C200H-LK201(-V1),
C500-LK203,
C500-LK201-V1,
C120-LK201-V1



D-sub 25-pin (male) M2.6 screw D-sub 25-pin (male) M2.6 screw

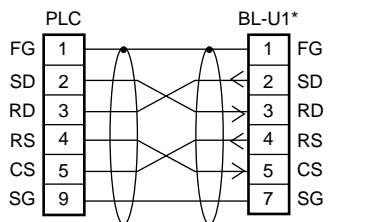
Connection with C20H,
C28H,
C40H



D-sub 9-pin (male) M2.6 screw D-sub 25-pin (male) M2.6 screw

* KEYENCE option OP-22149 (1.5 m) or commercially available cross cable can be used.

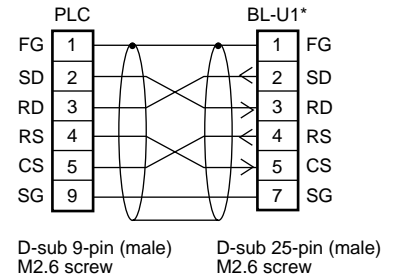
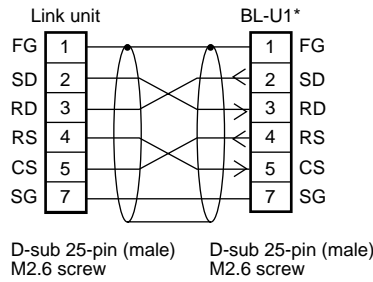
Connection with C200HS-CPU21/23/31/33,
CQM1-CPU21/41/42/43/44,
C200HE-CPU32/42,
C200HG-CPU33/43/53/63,
C200HW-COM02/COM04/COM05/COM06
C200HX-CPU34/44/54/64,
C200HX-CPU65-Z/85-Z



D-sub 9-pin (male) M2.6 screw D-sub 25-pin (male) M2.6 screw

■ **SYSMAC-CV Series**

Connection with CV500-LK201(Port 1) Connection with CV500-LK201 (Port 2),
CV500,
CV1000,
CVM1



* KEYENCE option OP-22149 (1.5 m) or commercially available cross cable can be used.

3

3.1.5 Wiring the RS-422A

Note 1: The cable can be extended to within 1.2 km.

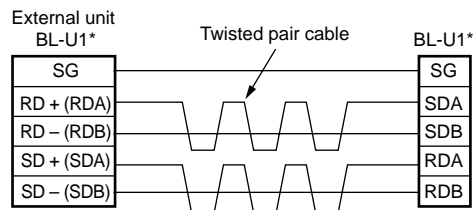
Note 2: Turn ON the terminators (BL-U1/external unit terminal resistance: 100 Ω).

⇨ See page 17.

Connect the BL-U1 to other devices with the following wiring.

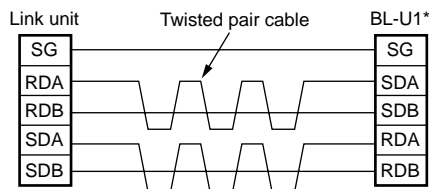
■ **Connecting a general RS-422A unit**

Use the same wiring when connecting the BL-U1 to the BL-U1*.



■ **Connecting the MELSEC-A Series**

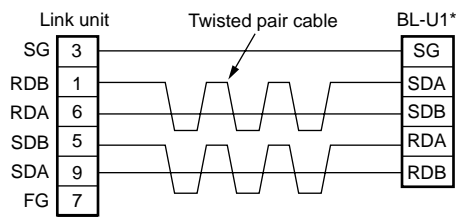
Connecting with AJ71(U)C24(-S□),
AJ71QC24-R4,
A0J2-C214-S1,
A1SJ71(U)C24-R4



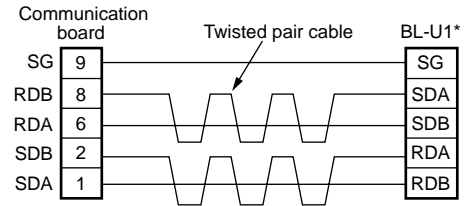
■ Connecting SYSMAC-C Series

Connecting with C200H-LK202 (-V1),
C500-LK201-V1,
C500-LK203,
C120-LK202-V1

Connecting with C200HW-COM03/COM06



D-sub 9-pin (male)
M2.6 screw

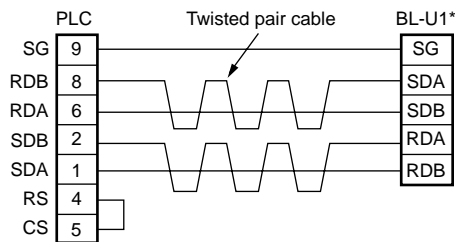


D-sub 9-pin (male)
M2.6 screw

3

■ Connecting SYSMAC-CV Series

Connecting with CV-500-LK201,
CV500,
CV1000,
CVM1



D-sub 9-pin (male)
M2.6 screw

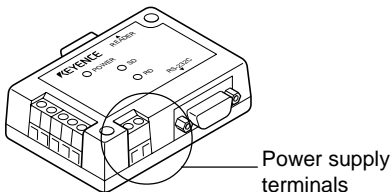
3.2 Connecting the BL-U2/N-42 and Wiring

This section describes the connection and wiring of the BL-600 Series and peripheral devices when the special power supply unit BL-U2 or N-42 is used.

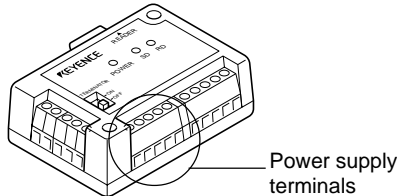
3.2.1 Connecting the BL-U2/N-42, AC power supply, and BL-600 Series

1. Connect the 24 V DC power supply to the power supply terminals of the BL-U2 or N-42.

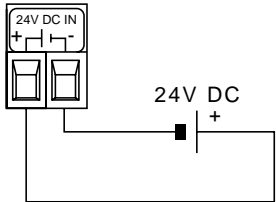
BL-U2



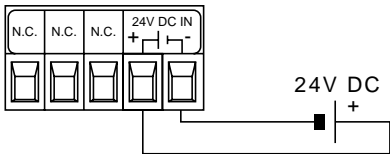
N-42



Power supply terminals



Power supply terminals

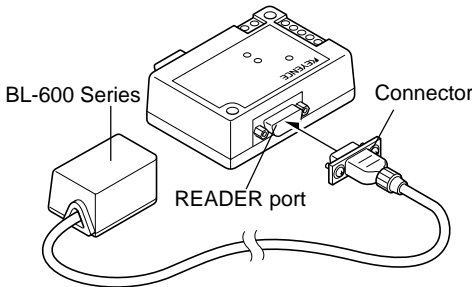


Make sure that the power supply provides 24 V DC. If the power supply output is not 24 V DC, it can damage the unit.

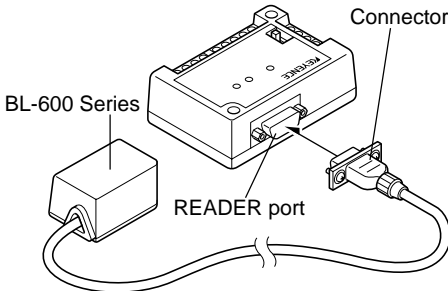
Note: If the power supply is UL rated, it must provide Class 2 output.

2. Connect the BL-600 Series to the READER port of the BL-U2 or N-42.

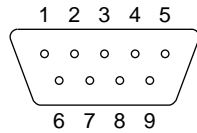
BL-U2



N-42



■ BL-U2/N-42 READER port pin assignment



D-sub 9-pin (male)
DCE specification (defined as terminal)
#4-40 screw (female)

Pin No.	Symbol	Function	Signal direction
1	TIM	Trigger input	Output
2	RD (RXD)	Sends RS-232C data	Output
3	SD (TXD)	Receives RS-232C data	Input
4	OK	OK signal	Input
5	GND (SG)	Ground (Common ground for respective signal)	—
6	NG	NG signal	Input
7	RS (RTS)	Ready to send RS-232C data	Input
8	CS (CTS)	Request to send RS-232C data	Output
9	+5 V	+5 V power supply	Output

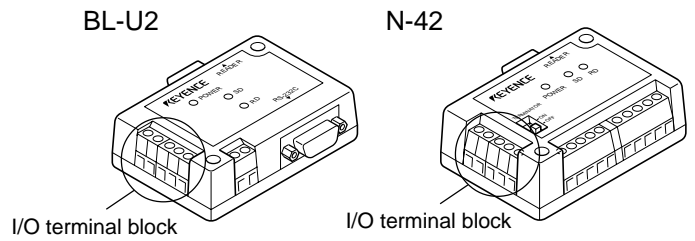
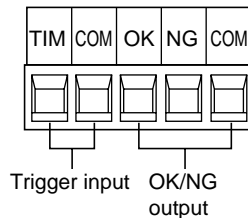
Note: Do not extend a power cable. A long power cable can cause a voltage drop, preventing the BL-600 from starting properly.

3.2.2 Terminals of I/O terminal block and connections

Terminals of the I/O terminal block

The terminals of the I/O terminal block are assigned as shown in the figure.

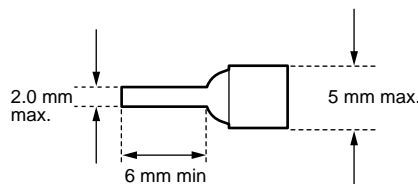
■ Terminal assignment



Symbol	Description	Signal direction
TIM	Trigger input	Input
COM	Common terminal for trigger input	Input
OK	OK output	Output
NG	NG output	Output
COM	Common terminal for output	Output

Applicable terminals

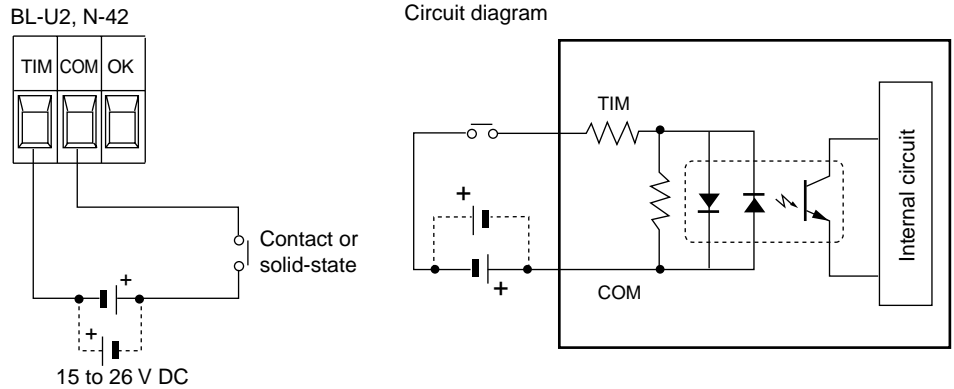
Use the following solderless contact pin (I-terminal) for connection.



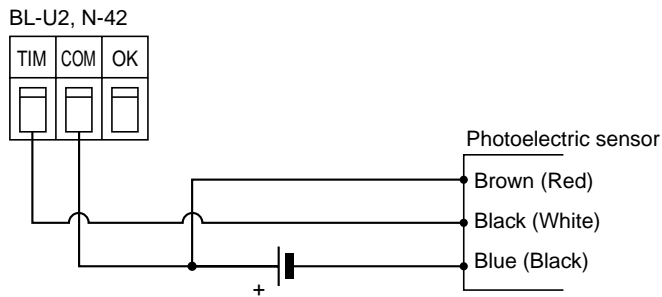
Recommended product
Manufacturer: Japan Solderless Terminal (J.S.T.) Mfg. Co., Ltd.
Model: VTUB-1.25

Connecting trigger input

The trigger input allows the BL-600 to start reading bar codes (turn on the laser beam). To turn ON the trigger input, supply 15 to 26 V DC between the trigger input terminals.



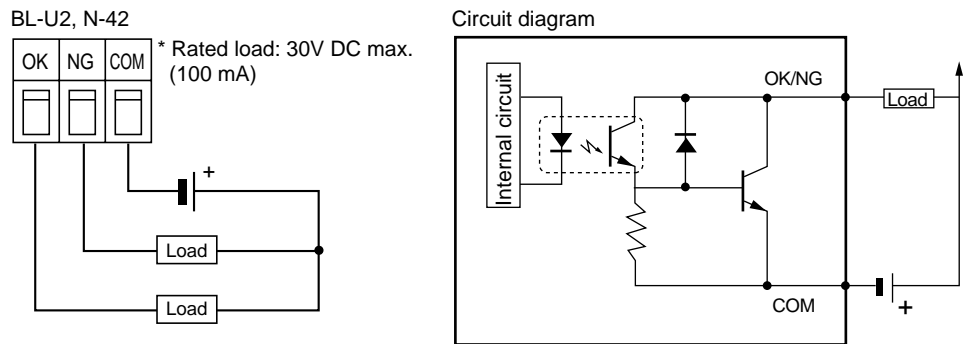
■ Connection to a photoelectric sensor manufactured by KEYENCE



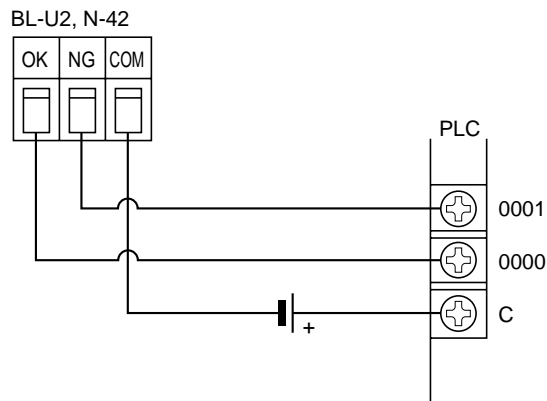
Connecting the OK/NG output

The OK/NG output is used to differentiate between acceptable and unacceptable results based on a comparison with preset data. (⇒ See page 101.) It can also be used to indicate whether or not the BL-600 Series successfully reads bar codes when there is no preset data entered.

The OK/NG output is an NPN open-collector output.



■ Connection to a programmable logic controller (PLC) manufactured by KEYENCE

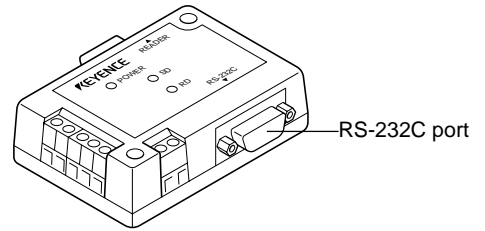
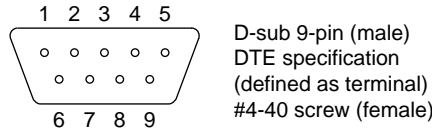


3.2.3 Connecting RS-232C (BL-U2)

Pin assignment of the RS-232C port

The BL-U1 has a RS-232C port with the following pin assignment.

■ RS-232C port pin assignment



Pin No.	Symbol	Function	Signal direction
2	RD (RXD)	Receive data	Input
3	SD (TXD)	Send data	Output
4	ER (DTR)	Connected to pin No.6 inside.	Output
5	SG	Signal ground	—
6	DR (DSR)	Connected to pin No.4 inside.	Input
7	RS (RTS)	Request to send data (always ON)	Output
8	CS (CTS)	Enable to send data	Input

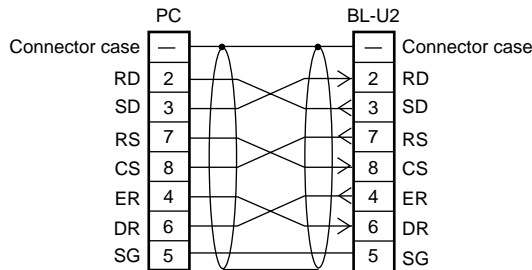
* One connector is provided.

Wiring the RS-232C cable

Connect the BL-U1 to a personal computer or other devices with the following wiring.

■ Connecting a PC

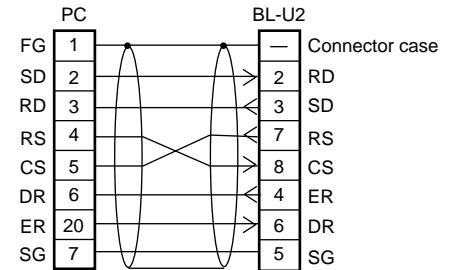
9-pin serial port



D-sub 9-pin (female) #4-40 screw D-sub 9-pin (female) #4-40 screw

* KEYENCE option cable OP-27937 (2 m) can be used.

25-pin serial port

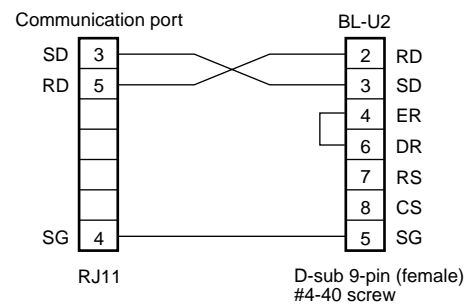


D-sub 25-pin (male) M2.6 screw D-sub 9-pin (female) #4-40 screw

* KEYENCE option OP-22149 (1.5 m) or OP-25057 (conversion connector) can be used.

■ Connecting NEW KV Series/Communication port

KV-10/16/24/40

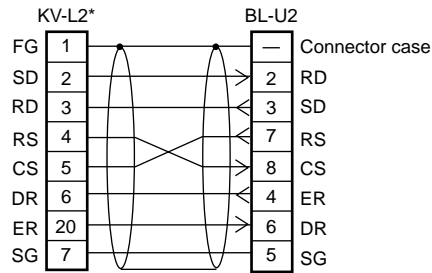


RJ11 D-sub 9-pin (female) #4-40 screw

* KEYENCE option OP-96368 (2.5 m) and OP-96369 (conversion connector) can be used.

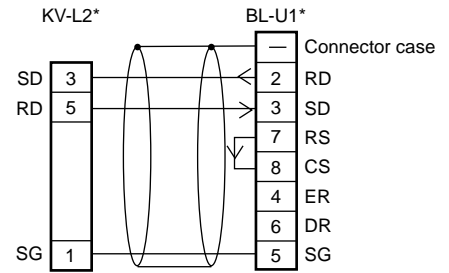
■ Connecting KV-L2*

Port 1



D-sub 25-pin (male) M2.6 screw D-sub 9-pin (female) #4-40 screw

Port 2



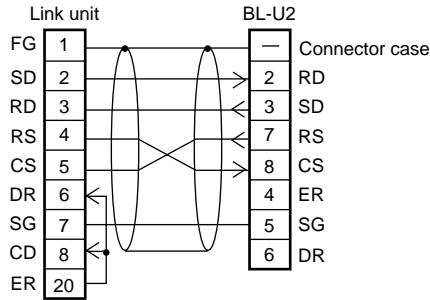
Terminal block D-sub 9-pin (female) #4-40 screw

* KEYENCE option OP-22149 (1.5 m) and OP-25057 (conversion connector) can be used.

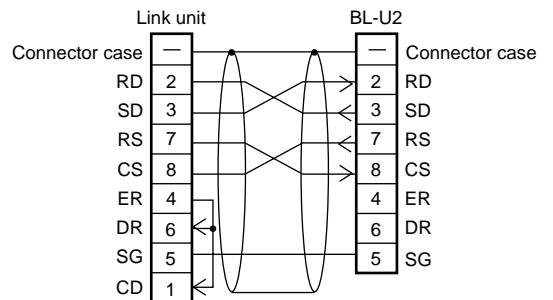
■ Connecting MELSEC-A Series

Connection with AJ71(U)C24(-S□), AJ71QC24-R2, A0J2-C214-S1

Connection with A1SJ71(U)C24-R2/PRF, A2CCPUC24(-PRF)



D-sub 25-pin (male) M2.6 screw D-sub 9-pin (female) #4-40 screw



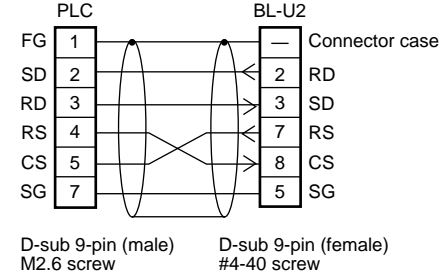
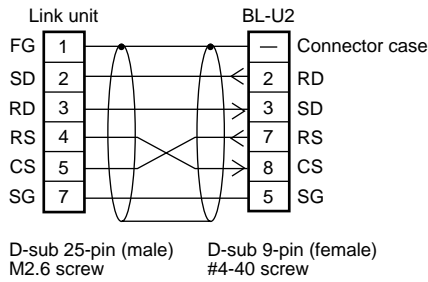
D-sub 9-pin (male) M2.6 screw D-sub 9-pin (female) #4-40 screw

3

■ SYSMAC-C Series

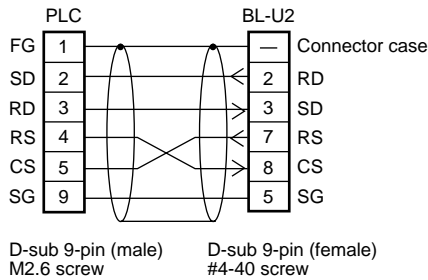
Connection with C200H-LK201(-V1),
C500-LK203,
C500-LK201-V1,
C120-LK201-V1

Connection with C20H,
C28H,
C40H



* KEYENCE option OP-22149 (1.5 m) and OP-25057 (conversion connector) can be used.

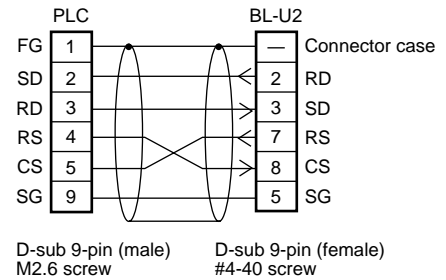
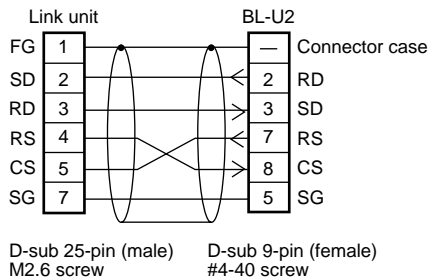
Connection with C-200HS-CPU21/23/31/33,
CQM1-CPU21/41/42/43/44,
C-200HE-CPU32/42,
C200HG-CPU33/43/53/63,
C200HW-COM02/COM04/COM05/COM06
C200HX-CPU34/44/54/64,
C200HX-CPU65-Z/85-Z



■ SYSMAC-CV Series

Connection with CV500-LK201(Port 1)

Connection with CV500-LK201 (Port 2),
CV500,
CV1000,
CVM1



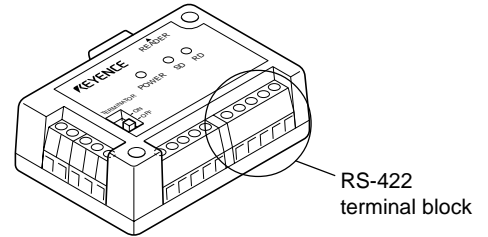
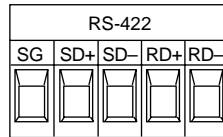
* KEYENCE option OP-22149 (1.5 m) and OP-25057 (conversion connector) can be used.

3.2.4 Connecting the N-42 to RS-422A

RS-422 terminal block assignment

The terminals of the RS-422A terminal block of the N-42 are assigned as shown in the figure.

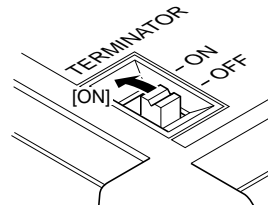
■ **RS-422 terminal block assignment**



Code	Description	Signal direction
SG	Ground	—
SD+	Sends data to + terminal.	Output
SD-	Sends data to - terminal.	Output
RD+	Receives data from + terminal.	Input
RD-	Receives data from - terminal.	Input

Note 1: The cable can be extended to within 1.2 km.

Note 2: Turn ON the terminators (BL-U1/external unit terminal resistance: 100 Ω).

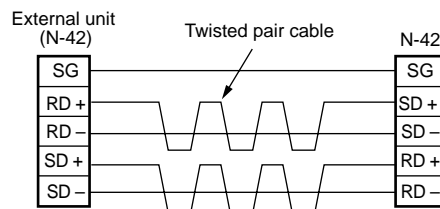


Wiring the RS-422A

Connect the N-42 to other devices with the following wiring.

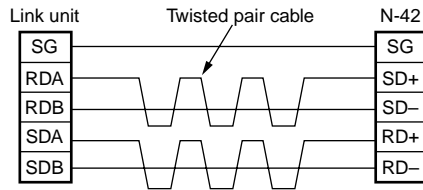
■ **Connecting a general RS-422A unit**

Use the same wiring when connecting the N-42 to the N-42.



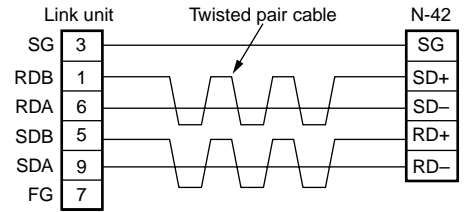
■ Connecting the MELSEC-A Series

Connecting with AJ71(U)C24(-S□),
AJ71QC24-R4,
A0J2-C214-S1,
A1SJ71(U)C24-R4



■ Connecting SYSMAC-C Series

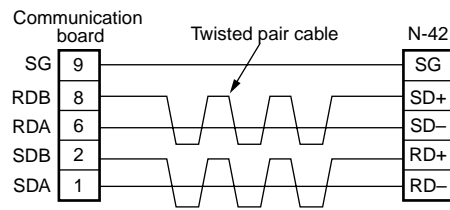
Connecting with C200H-LK202 (-V1),
C500-LK201-V1,
C500-LK203,
C120-LK202-V1



D-sub 9-pin (male)
M2.6 screw

■ Connecting SYSMAC-C Series

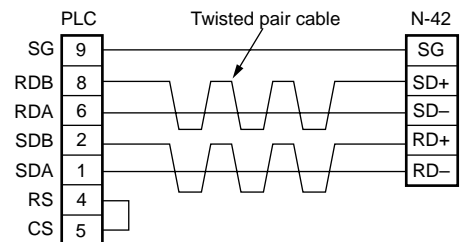
Connecting with C200HW-C0M03/CPM06



D-sub 9-pin (male)
M2.6 screw

■ Connecting SYSMAC-CV Series

Connecting with CV-500-LK201,
CV500,
CV1000,
CVM1



D-sub 9-pin (male)
M2.6 screw

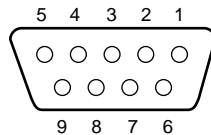
3.3 Wiring without the Special Power Supply Units

This section describes the connection and wiring of the BL-600 Series and peripheral devices when a special power supply unit is not used.

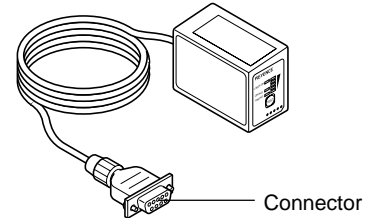
3.3.1 Pin assignments of the BL-600 Series connector and the connecting power supply

Pin assignment of the BL-600 Series power supply connector

■ Connector pin assignment



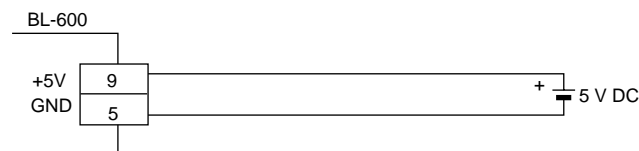
D-sub 9-pin
(female)
#4-40 screw (male)



Pin No.	Cable color	Symbol	Description	Signal direction
Connector case	Shield	FG	Frame ground	—
1	Yellow	TIM	Trigger input	Input
2	Brown	RD (RXD)	Receives RS-232C data	Input
3	Purple	SD (TXD)	Sends RS-232C data	Output
4	White	OK	OK output	Output
5	Black	GND (SG)	Ground (Common ground for respective signals)	—
6	Gray	NG	NG output	Output
7	Pink	RS (RTS)	Request to send RS-232C data (always ON)	Output
8	Blue	CS (CTS)	Enable to send data through RS232C	Input
9	Red	+5 V	+5 V power supply	Input

Power supply connections

Connect the 5 V DC power supply to the power supply connector of the BL-600 Series.



- **Be sure to match the polarities of the power supply when soldering the connections. Reversing the polarities will damage the unit.**
- **Make sure that the power supply provides a stable 5 V DC \pm 5%. If the power supply does not function in the above range, it can damage the unit.**

Note1: Do not extend the power cable. A long power cable can cause a voltage drop, preventing the BL-600 from starting properly.

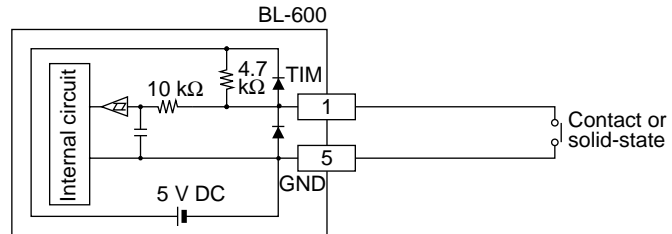
Note2: If the power supply is UL rated, it must provide Class 2 output.

3.3.2 I/O Wiring

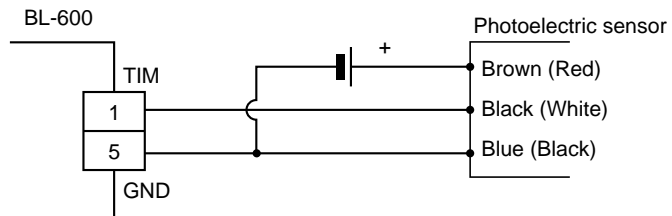
Trigger input

The trigger input is used to signal the BL-600 to start reading (start laser emission). The trigger input is a non-voltage input (TTL input is also available with negative logic).

Circuit diagram



■ Connection to a photoelectric sensor manufactured by KEYENCE

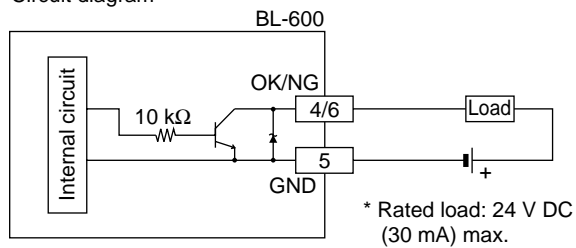


OK/NG output

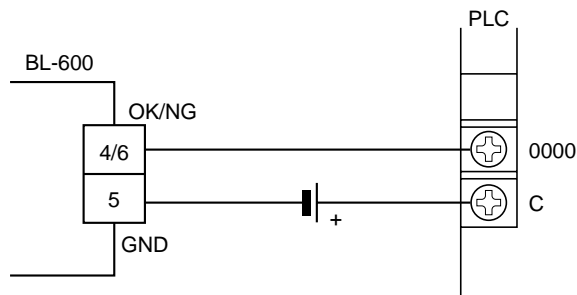
The OK/NG output is used to display the comparison/verification result of the preset data. ⇨ See page 101.

When no preset data is registered, it can be used to display whether or not bar codes are being read correctly. The output form is NPN open-collector.

Circuit diagram



■ Connection to a programmable logic controller (PLC) manufactured by KEYENCE

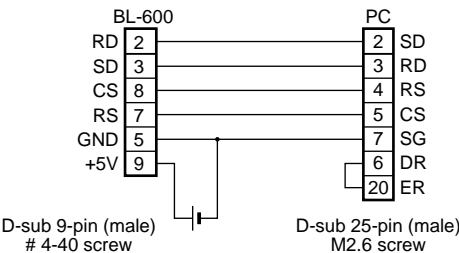
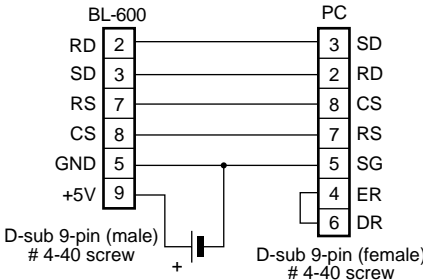


3.3.3 RS-232C connection

Wire the RS-232C as indicated below when connecting the BL-600 to a PC.

Connecting the computer with 9-pin

Connecting the computer with 25-pin



Chapter 4

Setup Software

This chapter describes the usage of the setup software to set or perform reading tests of the BL-600 Series.

4.1	Installing and Operating the Setup Software	38
4.1.1	Installation and operation procedures	38
4.1.2	Installing setup software	39
4.1.3	Installation/Start-up	39
4.1.4	Initial screen	40
4.1.5	Basic operation	41
4.2	Setup Procedure	42
4.2.1	Model selection	42
4.2.2	[[Main]] (Operation setting) screen	42
4.2.3	[[Comm Settings-1]] (Communication parameters 1) screen	45
4.2.4	[[Comm Settings-2]] (Communication parameters 2) screen	46
4.2.5	[[Code setup]] (Bar code setting) screen	49
4.2.6	[[Utility]] screen	53
4.3	Sending/Receiving Settings	54
4.3.1	Sending/receiving settings to/from the BL-600 Series	54
4.3.2	Sending/receiving settings to/from the BL-600 Series via the N-400	57
4.4	Reading/Saving/Printing File	59
4.4.1	[[Files] screen	59
4.4.2	Reading a previously saved setting file	59
4.4.3	Saving updated settings in a file	60
4.4.4	Comparing the contents of the file currently being edited with a saved file	61
4.4.5	Printing contents of a setting file	61
4.4.6	Resetting the edited settings to the initial (factory) settings...	62
4.5	Using Monitor	62
4.5.1	Receiving data and checking the result	62
4.5.2	Command transmission	63
4.5.3	Starting the test mode	65
4.5.4	Changing the scanning width	66
4.6	List of Error Messages	67
4.7	Example of Printing from the Setup Software	68

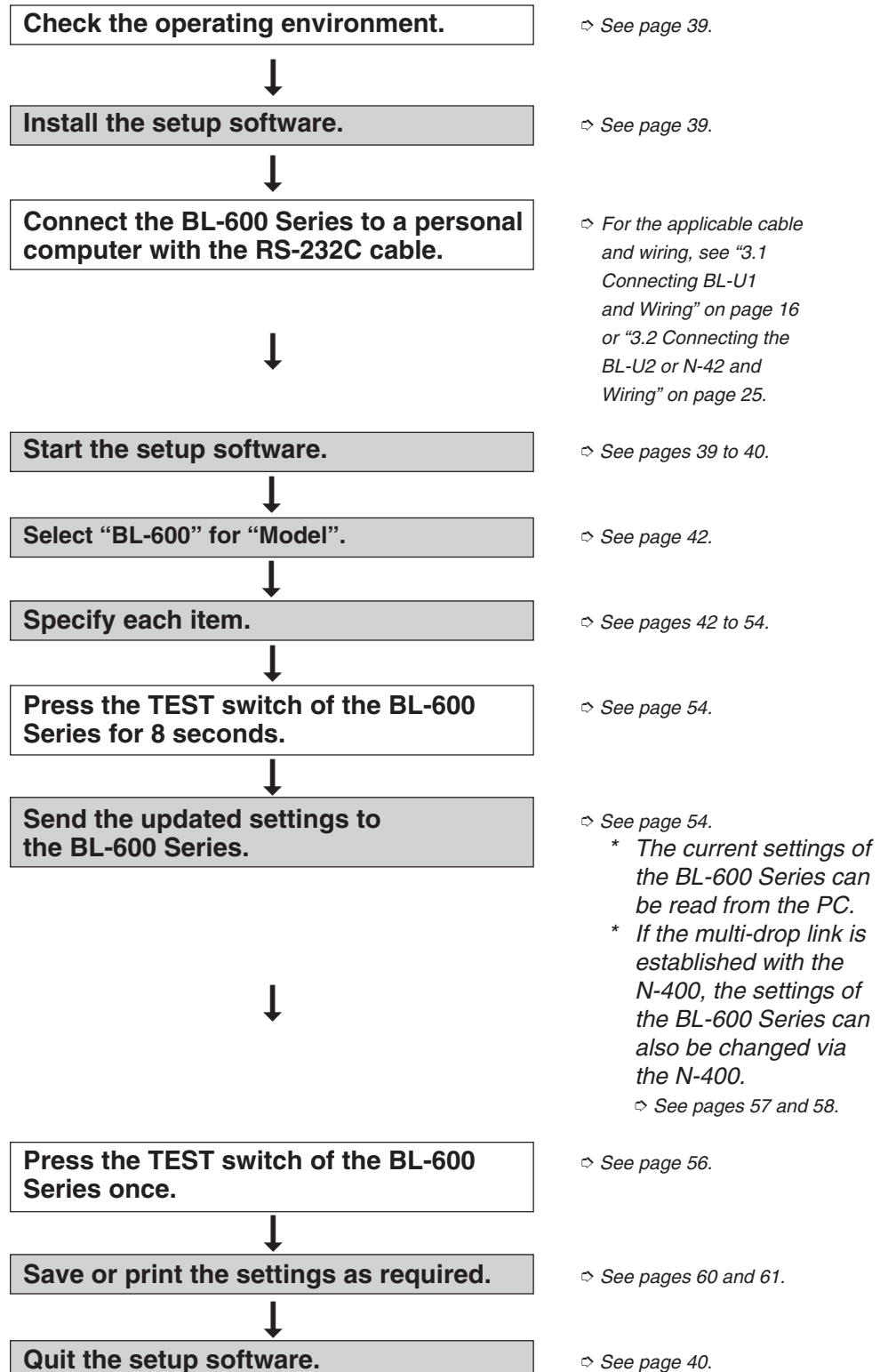
4.1 Installing and Operating the Setup Software

This section describes the installation and operation procedures of the setup software.

4.1.1 Installation and operation procedures

The following chart shows the installation and setup procedures of the setup software.

* The shaded boxes indicate an operation of the setup software or a personal computer.

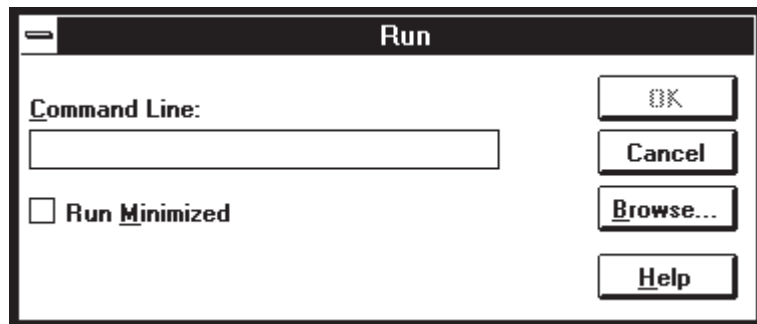


4.1.2 Installing setup software

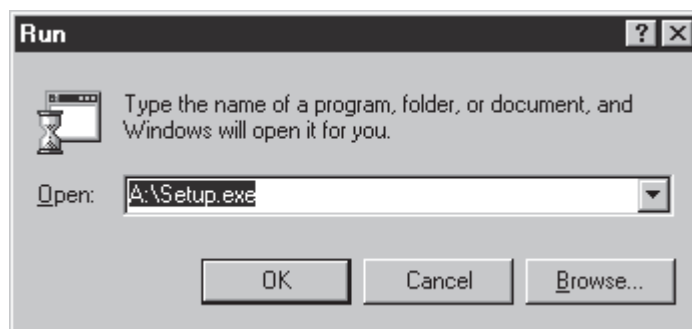
Items	Requirements
PC	IBM PC/AT
OS	MS-Windows 3.1 MS-Windows 95 MS-Windows 98
Floppy disk drive	3.5 inch floppy disk drive (1.44 MB compatible)
Display	Resolution 640 x 480 or higher
Serial port	A minimum of one RS-232C port is required.

4.1.3 Installation/Start-up

1. Insert the BL-600 setup software system disk into the floppy drive.
2. Perform the following procedure.
 - Windows 3.1:
Execute "Run..." in the icon menu of the program manager.



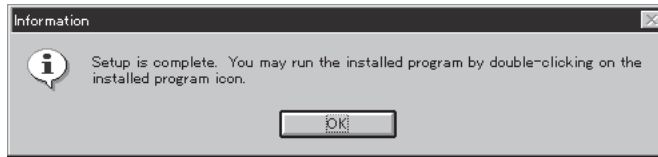
- Windows 95/98:
Select "Run" from the "Start" menu.



3. Run the "SETUP" file from the floppy disk drive.
Type in as follows:
A: \SETUP
4. The setup software installer starts. Follow the instructions of the installer program.
Typically, clicking [Next (N)>] twice will complete the installation procedure.
5. Specify the directory to install the setup software into.
The setup software is normally installed in the following directory.
C: \KEYENCE\BLSET
If this directory is correct, click on [Next (N)]. If you wish to change the directory, click on [Browse (R)..], and select the desired directory.

6. Completing the installation

- (1) When the installation begins, the file copy process is displayed as a graph.
- (2) When the installation is complete, the following message appears.



7. Start the setup software.

For Windows Ver. 3.1, double-click the “BL” icon in the “KEYENCE” group.
 For Windows 95/98, start the program from the Start Menu.

4.1.4 Initial screen

This section describes the initial screen of the setup software.

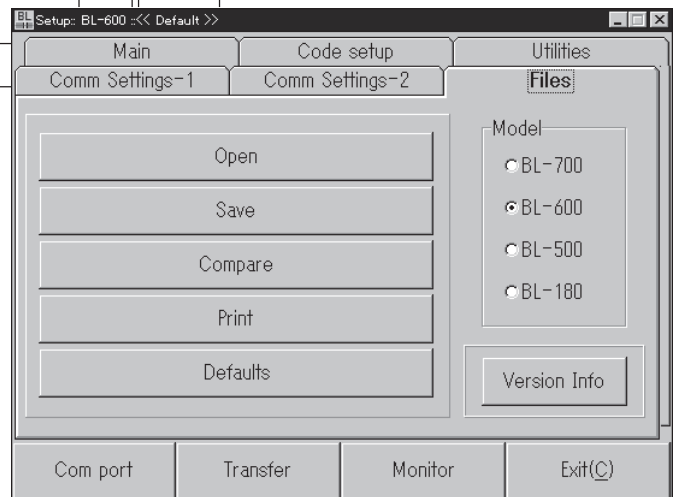
Shows the name of the stored file currently being edited, or the status of the item currently being changed.

Operating status	Indication
All settings have the initial values.	<<Default>>
The file is read from the PC memory.	<<File: (File name)>>
The file is read from the BL-600 series.	<<BL:>>
One or more items have changed from the initial settings or from the status they were at when the file was read from memory.	(changed)

Shows the model of the bar code reader that is currently selected.

Shows the setting options.

- Main (Operation setting:)**
 ⇨ See pages 42 to 44.
- Comm Settings-1 (Communication parameters 1:)**
 ⇨ See page 45.
- Comm Settings-2 (Communication parameters 2:)**
 ⇨ See page 46 to 48.
- Code setup (Bar code setting:)**
 ⇨ See pages 49 to 52.
- Utilities:**
 ⇨ See pages 53 to 54.
- Files:**
 ⇨ See pages 59 to 62.



- Com port:**
 ⇨ See pages 55 and 57.
- Transfer:**
 ⇨ See pages 55 to 57.
- Monitor:**
 ⇨ See pages 62 to 66.
- Exit:**
 Click this button to quit the setup software.

4.1.5 Basic operation

This section describes the basic operation of the setup software.

■ Selecting items

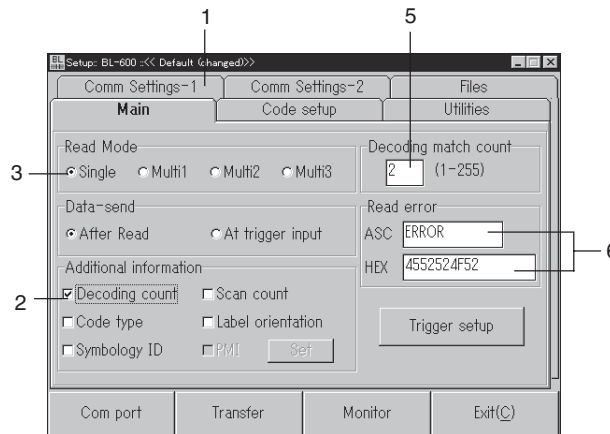
Place the arrow (mouse pointer) on the item to be changed, and click the mouse.

■ Boxes and buttons

Example

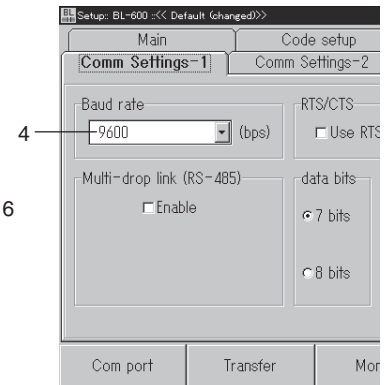
[[Main]]

(Operation setting)



[[Comm Settings-1]]

(Communication parameters 1)



Indication		Operation
1		Click on the tab to select the setting options.
2	<input checked="" type="checkbox"/>	Click the check box to select items. <input checked="" type="checkbox"/> ...The item is selected. <input type="checkbox"/> ...The item is not selected. * With Windows Ver. 3.1, the enabled function is indicated as <input checked="" type="checkbox"/> .
3	<input checked="" type="radio"/>	Click the radio button to select items. <input checked="" type="radio"/> ...The item is selected. <input type="radio"/> ...The item is not selected.
4		Used to select one of several options. Click at the side of the box to display the pull-down menu. Click the desired item from the menu.
5	<input type="text" value="2"/> (1-255)	Enter the desired values in the text box. Click in the box and enter a numerical value using the keyboard. * If the entered value exceeds the available range, an error message appears. ⇨ See page 67.
6	ASC: <input type="text" value="ERROR"/> HEX: <input type="text" value="4552524F52"/>	Enter characters in the text box. Click in the box and enter characters using the keyboard. The box labeled "HEX" accepts the entry of hexadecimal numbers (00 to 7F) from the keyboard. Use this box to enter control characters ("00" to ""21h" of the ASCII code table, such as [CR] and [STX]). * If the entered value exceeds the available range, an error message appears. ⇨ See page 67.

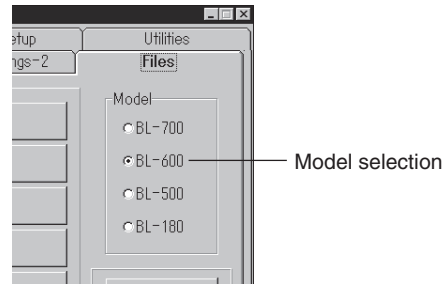
4.2 Setup Procedure

This section describes each of the setting options.

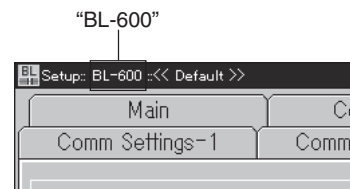
4.2.1 Model selection

Select the model of the bar code reader on the **[[Files]]** screen.

1. Click “BL-600” for “Model”.

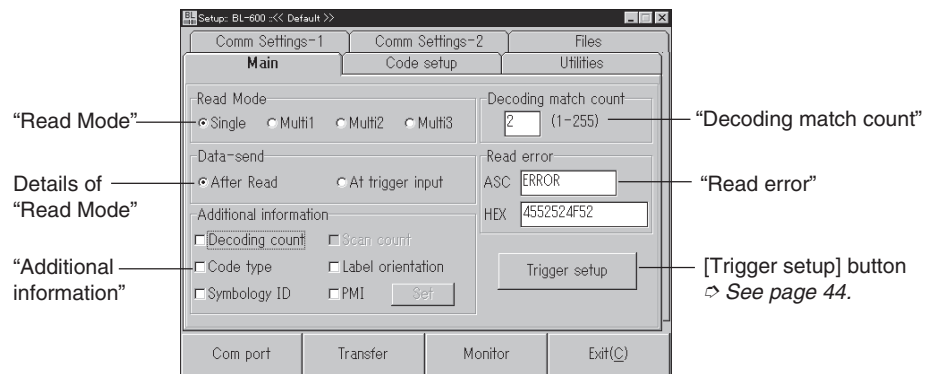


2. Check to see if “BL-600” appears as the title of the dialog box.



4.2.2 **[[Main]]** (Operation setting) screen

1. Set the following items.



“**Read Mode**” ⇨ See pages 88 to 92.

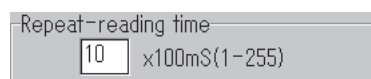
Select a “Read Mode”.

Details of “Read Mode”

- If “Single” is selected:
The following box appears. Select the “Data-send” option. ⇨ See page 88.



- If “Multi 1” or “Multi 2” is selected:
The following box appears. Specify a “Repeat-reading time” ⇨ See page 89.
within the range of 1 to 255 (100 ms to 25.5 s).



- If “Multi 3” is selected:
Nothing appears.

“Additional information” ⇨ See pages 102 to 106.

Select the items as required.

* “Scan count” only appears when “Decoding count” is selected.

When “PMI” is selected:

Click the [Set] button to display the “PMI output setting” screen.
Specify a value within the range of 0 to 100 for each item.

⇨ See pages 104 to 106.

“Decoding match count”

Enter a desired value within the range of 1 to 255 (times).

Specifying a large number for “Decoding match count” increases the reliability of the reading, but decreases the reading speed.

Specifying a small number for “Decoding match count” increases the reading speed, but decreases the reliability of the reading.

Typically, the initial value “2” is used.

“Read error”

Specify the error code that the BL-600 Series will send to the personal computer if it fails to read a bar code.

This code can be changed as desired using 8 or less characters.

Typically, the initial setting of “ERROR” is used.

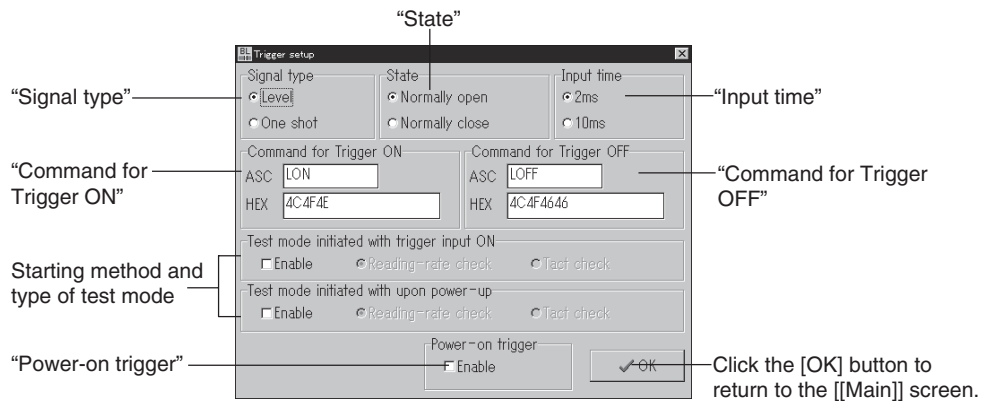
If the text box is left empty, the BL-600 Series will not send a read error code.

Reference: “Decoding match count”

The BL-600 Series judges that a bar code has been properly read when the number of scans for successful decoding (reading) of the bar code (Decoding count) reaches the value specified in “Decoding match count”.

2. Set the items for [Trigger setup].

When the [Trigger setup] button is clicked, the “Trigger setup” screen appears. Set the following items.

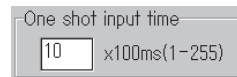


“Signal type” ⇨ See pages 86 and 87.

Select a “Signal type”.

- If “One shot” is selected:

The “One shot input time” setting box appears. Specify a value for the input time within the range of 1 to 255 (100 ms to 25.5 s).



“State”

Select whether to emit a laser beam when the trigger input is on (Normally-open) or when the trigger input is off (Normally-closed).

Starting method and type of test mode

Select this option to start the test mode if the trigger input is on or if the BL-600 Series is turned on. Normally, this option is not selected.

- * If “Test mode initiated with trigger input ON” is selected, the trigger input cannot function normally.

“Power-on trigger”

- If “Enable” is not selected:

The BL-600 Series does not emit a laser beam for 5 seconds after it is turned on, even if the trigger input turns on.

- If “Enable” is selected:

The BL-600 Series emits a laser beam immediately after being turned on if the trigger input turns on.

Select this option to activate the laser beam continuously once the BL-600 Series has been turned on.

“Command for Trigger ON”/“Command for Trigger OFF” ⇨ See page 115.

Set the characters for the command used to control the reading operation (Laser ON/OFF) with command communication.

Any number of characters, up to 8, can be set. Normally, the initial setting (LON: Trigger ON, LOFF: Trigger OFF) should be used.

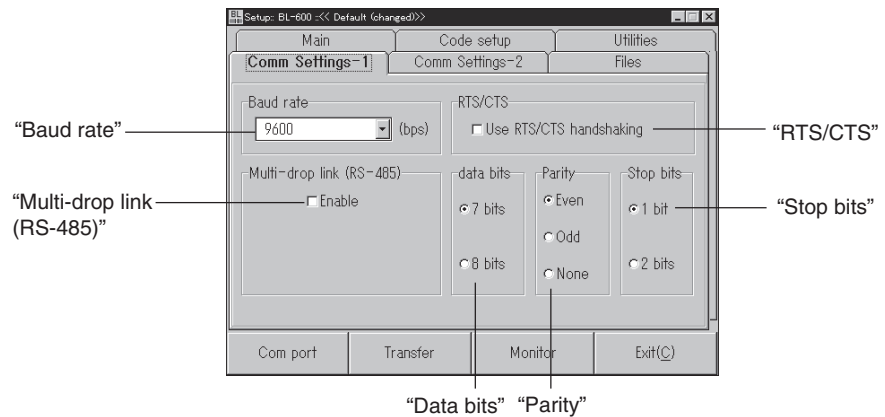
“Input time”

Specify the ON time of the trigger input to enable the signal.

Specify “10 ms” to ignore chattering of the contact when a contact type output (relay, etc.) is used for the trigger input.

4.2.3 [[Comm Settings-1]] (Communication parameters 1) screen

Set the following items.



“Baud rate”

“Data bits”

“Stop bits”

“Parity”

Set these communication parameters according to the settings of the external devices that will be connected (PC, PLC, etc.).

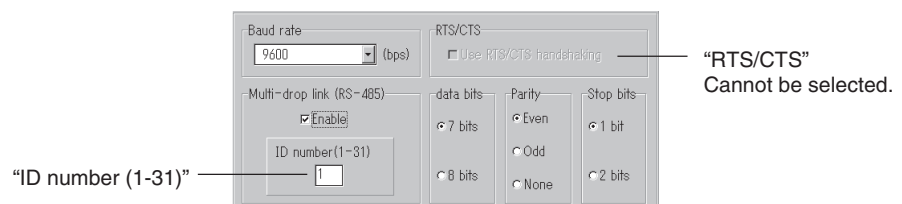
“Multi-drop link (RS-485)”

⇒ See “Multi-drop controller N-400 User’s Manual”.

1. Select “Enable” to use multi-drop link.

* If the multi-drop link is enabled, “RTS/CTS” is disabled.

2. The “ID number (1-31)” setup box appears. Specify the ID number as a value between 1 to 31. Be sure not to set the same number for different BL-600 units in the same multi-drop link.



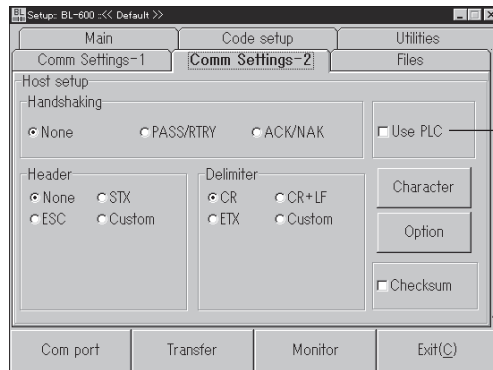
“RTS/CTS” ⇒ See page 112.

Select “RTS/CTS” to suspend read data transmission with the CTS signal of RS-232C.

4.2.4 [[Comm Settings-2]] (Communication parameters 2) screen

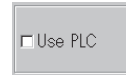
PLC link setting

The settings vary depending on whether or not the PLC link will be used. First, select whether or not to use the PLC link with “Use PLC”.



“Use PLC”

- If the PLC link is not used:
⇨ See page 46.



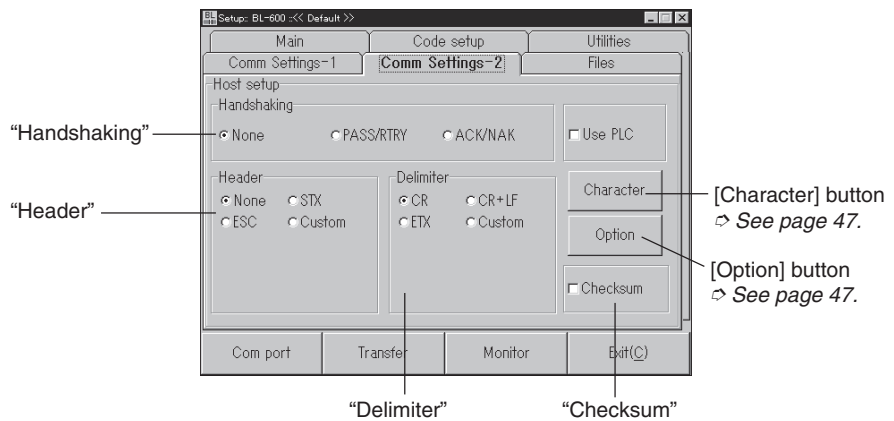
- If the PLC link is used:
⇨ See page 48.



4

If the PLC link is not used

1. Set the following items.



“Handshaking” ⇨ See pages 111 and 112.

Select the type of communication forms (communication protocol) to send the read bar code data from the BL-600 Series to the personal computer.

“Checksum” ⇨ See pages 167 and 168.

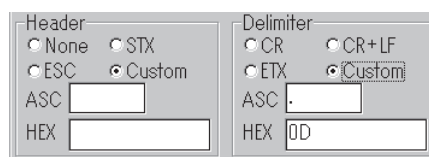
You can add data to check for incorrect data translation, such as garbled characters in the serial communication.

“Header”

“Delimiter” ⇨ See page 113.

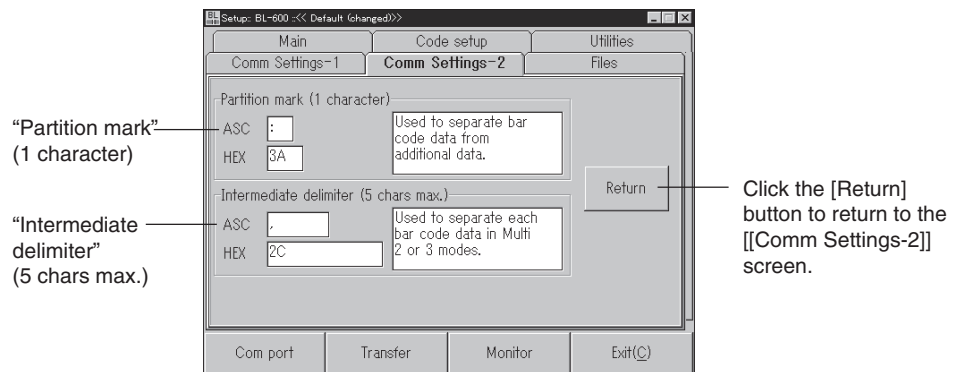
Select the transmission format to send the read bar code data.

If “Custom” is selected, the following text boxes appear. Type the desired header and delimiter (up to 5 characters) in each box.



2. Set the items for [Character].

When the [Character] button is clicked, the following screen appears. Set each item.



“Partition mark (1 character)”

Specify the partition mark to separate the bar code data read with the BL-600 Series and additional information. ⇨ See pages 102 to 106. Any one character can be used. Normally, the initial setting of (:) should be used.

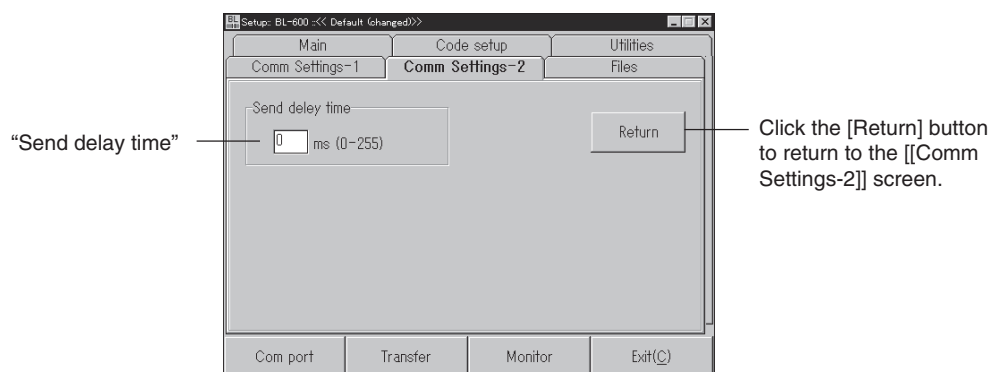
“Intermediate delimiter (5 chars max.)”

Specify the intermediate delimiter to separate each bar code data read in “Multi-label read mode 2” (⇨ See page 90.) or “Multi-label read mode 3”. ⇨ See page 91.

Any characters, up to 5, can be used. Normally, the initial setting of (.) should be used.

3. Set the item for [Option].

When the [Option] button is clicked, the following screen appears. Specify the “Send delay time”.



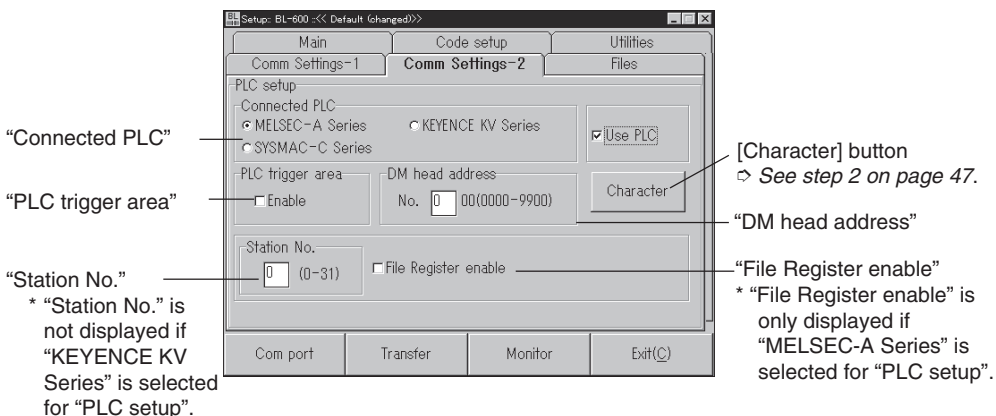
“Send delay time”

Specify the response time, within the range of 0 to 255 (ms), for the time between the instant the BL-600 Series receives a command from the PC and the instant the BL-600 Series sends back a response.

If the PLC link is used

Set the following items.

⇒ Refer to “Chapter 8, PLC Link” for details.



4

“Connected PLC”

Specify the model of the PLC to be connected.

“PLC trigger area” ⇒ See page 137.

Check “Enable” to send a trigger signal to the BL-600 Series using the PLC link.

“Station No.”

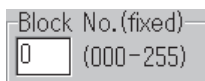
Specify a station number between 0 to 31.

“DM head address” ⇒ See page 135.

Specify a value for the head address of DM within the range of 0000 to 9900.

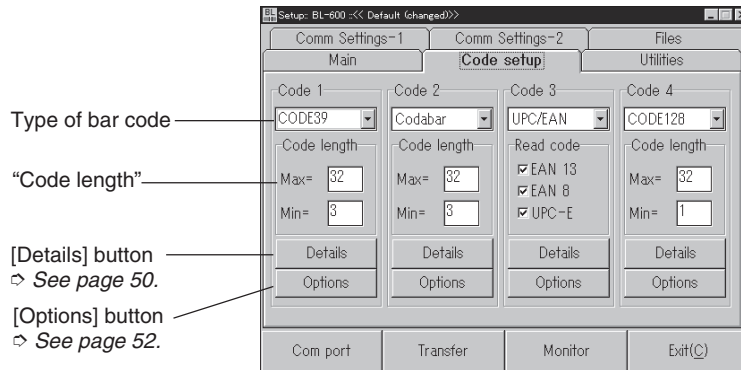
“File Register enable”

1. Select “File Register enable” to use the file register (⇒ See page 131.) as a device.
2. If the file register is enabled, the following screen appears. Specify a value, within the range of 000 to 255, for the block number of the file register to be used.



4.2.5 [[Code setup]] (Bar code setting) screen

1. Set the type of bar codes, readout digits and other functions.



Type of bar code

Select the type of bar code to be used.

- * If four different types of bar codes are specified in “Code 1” to “Code 4”, the BL-600 Series can read 4 types of bar codes without changing settings.

“Code length”

Specify the maximum number of digits for the bar code in “Max=” and the minimum number of digits in “Min=”.

- For “CODE39”
Specify a value, between 3 and 32, for the number of digits including the “*” (start/stop character) and a check digit.
- For “ITF”
Specify a value, between 2 and 32, for the number of digits including a check digit (even numbers only).
- For “(Industrial) 2of5” and “COOP 2of5”
Specify a value, between 1 and 32, for the number of digits including a check digit.
- For “Codabar”
Specify a value, between 3 and 32, for the number of digits including “a”, “b”, “c”, “d” (start/stop characters) and a check digit.
- For “UPC/EAN”
A setting for the number of digits is not required. Select whether or not to enable the reading of each of 13-digit EAN (UPC-A), 8-digit EAN, and UPC-E.
- For “CODE93”
Specify a value, between 1 and 32, for the number of digits without a start/stop code and a check digit.
- For “CODE128”
Specify the number of digits without a start/stop code, check digit, FUN1 to 4 (function codes), “SHIFT”, and “CODE-A/B/C”.
The available range varies depending on the type of start code (CODE-A to C).
 - CODE-A/B: 1 to 31 digits
 - CODE-C: 1 to 64 digits

Note 1: For “ITF”, “(Industrial) 2of5”, and “COOP 2of5”, be sure to fix the number of digits according to the bar code actually used. Otherwise, some digits may be skipped (not read) without recognition.

Example

To fix the number of digits to “8”
Specify “Max=” as “8” and “Min=” as “8”.

Note 2: It is recommended to fix the number of digits for “Codabar”. Some digits may be skipped depending on the print condition or the position of the bar code reader.

Note 3: When reading only one type of bar code, specify it in “Code 1” and leave the other boxes as “None”. This decreases the possibility of misreading.

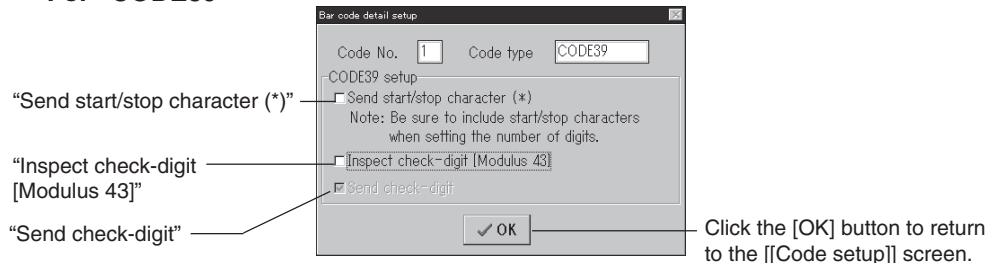
2. Set the items for [Detail].

When the [Detail] button of “Code 1” through “Code 4” is clicked, the “Bar code detail setup” screen appears.

Specify each item.

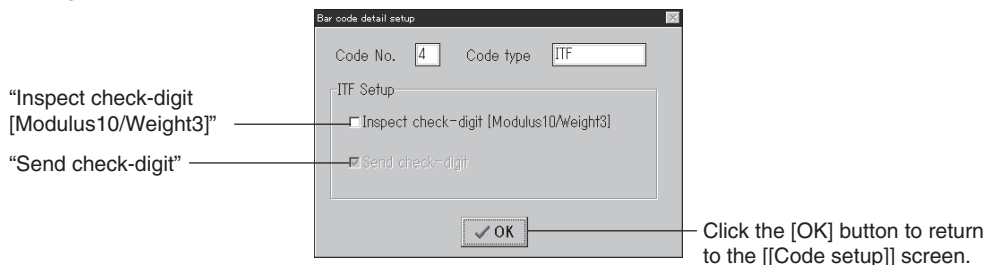
The items vary depending on the specified type of bar code.

For “CODE39”



- “Send start/stop character (*)”
If “Send start/stop character (*)” is set, the BL-600 Series adds an “*” (asterisk) to the read data and sends it to the PC.
- “Inspect check-digit [Modulus 43]”
If “Inspect check-digit [Modulus 43]” is set, the option “Send check-digit” is activated (displayed in black).
- “Send check-digit”
If “Send check-digit” is set, the BL-600 Series sends the read data with the check digit to the PC.

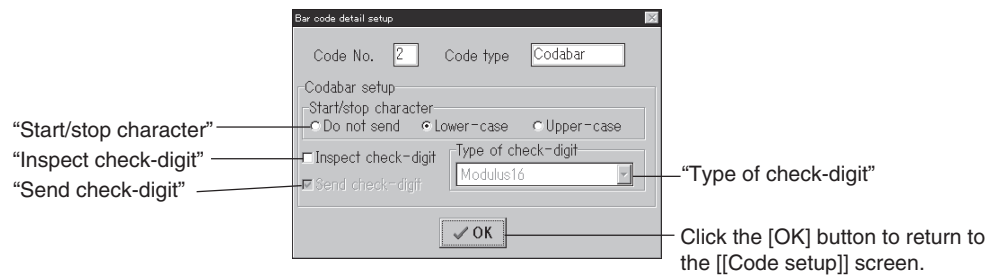
For “ITF”



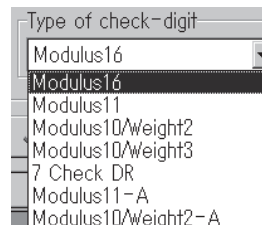
- “Inspect check-digit [Modulus10/Weight3]”
If “Inspect check-digit [Modulus10/Weight3]” is set, the option “Send check-digit” is activated (displayed in black).
- “Send check-digit”
If “Send check-digit” is set, the BL-600 Series sends the read data with the check digit to the PC.

Note: When reading a standard distribution code (bar codes on carton boxes), fix “Code length” to 14 or 16 digits in the [[Code setup]] screen and enable “Inspect check-digit [Modulus10/Weight3]”.

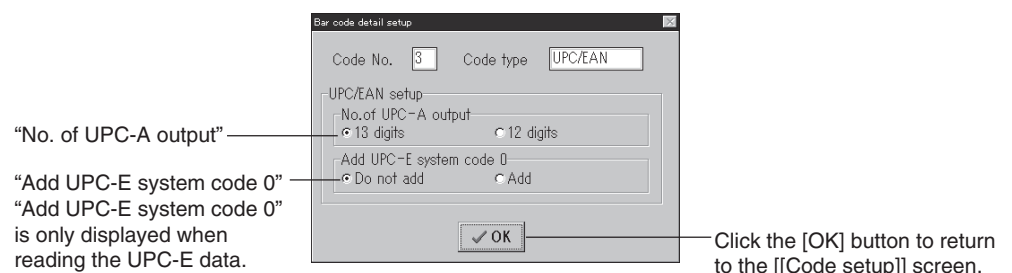
For “Codabar”



- “Start/stop character”
If “Lower-case” or “Upper-case” is set, the BL-600 Series adds an “a”, “b”, “c”, or “d” (lowercase or uppercase) to the read data and sends it to the PC.
- “Inspect check-digit”
If “Inspect check-digit” is set, the option “Send check-digit” is activated (displayed in black).
- “Send check-digit”
If “Send check-digit” is set, the BL-600 Series sends the read data with the check digit to the PC.
- “Type of check-digit”
Select the type of check digit to use.



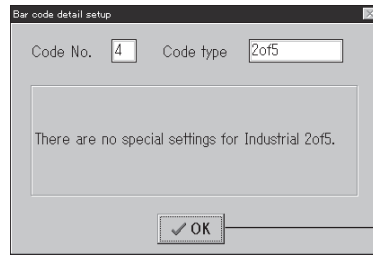
For “UPC/EAN”



- “No. of the UPC-A output”
Specify whether to use a 13-digit or a 12-digit output when reading the UPC-A data.
- “Add UPC-E system code 0”
If “Add” is selected, the BL-600 Series adds a “0” to the beginning of the data and sends it to the PC.

* The check digit setting is not provided on the screen, but the BL-600 Series internally calculates it using modulus 10/weight 3. (The data is sent.)

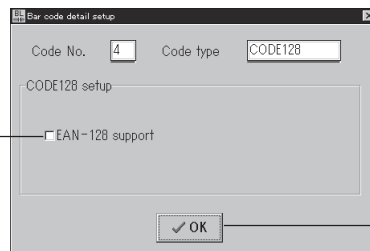
For “(Industrial) 2of5”, “COOP 2of5”, and “CODE93”



Click the [OK] button to return to the [[Code setup]] screen.

There are no detail setting parameters for these bar codes.

For “CODE128”



“EAN-128 support”

Click the [OK] button to return to the [[Code setup]] screen.

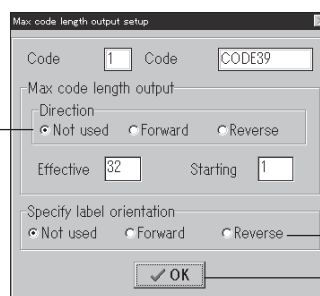
“EAN-128 support”

Check “EAN-128 support” to enable the BL-600 Series to accept the data configuration of EAN-128 specified as the international standard distribution code. ⇨ See page 166.

* The check digit setting is not provided on the screen, but the BL-600 Series internally calculates it using modulus 103. (The data is not sent.)

3. Set the items for [Options].

When the [Options] button is clicked for “Code 1” to “Code 4”, the “Max code length output setup” screen appears. Set each item.



“Max code length output”

“Specify label orientation”

Click the [OK] button to return to the [[Code setup]] screen.

“Max code length output” ⇨ See page 107.

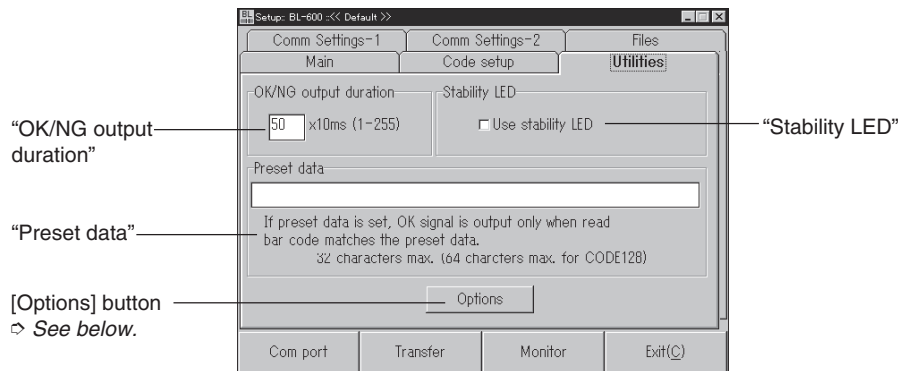
To output only the selected digit(s) from the read data, specify the direction in which to select (“Direction”), the digit at which to begin selection (“Starting”), and the number of digits to be selected (“Effective”).

“Specify label orientation” ⇨ See page 93.

If “Specify label orientation” is set, the BL-600 Series only reads bar codes moving with the specified orientation. Bar codes moving with any other orientation are not read.

4.2.6 [[Utility]] screen

1. Set the following items.



“OK/NG output duration”

Set the “OK/NG output duration” with a numerical value between 1 and 255 (10 ms to 2.55 s).

“Preset data” ⇨ See page 101.

Set the length, up to 32 characters, of the bar code data to be entered.
* If CODE-C is set for CODE128, up to 64 characters can be set.

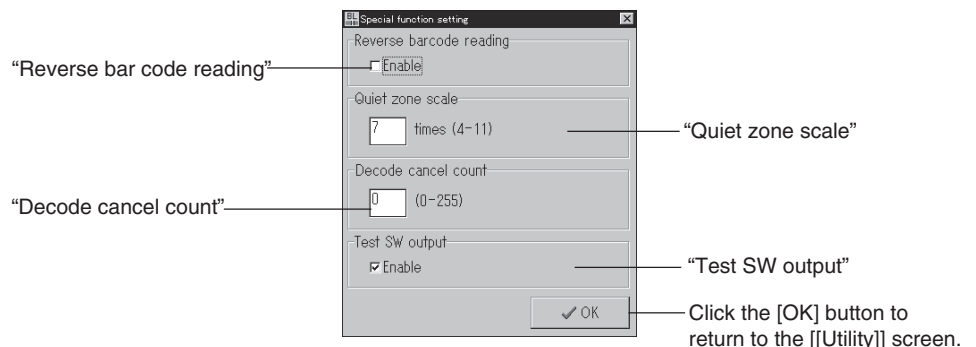
“Stability LED” ⇨ See page 99.

If “Use stability LED” is set, the BL-600 Series displays the STABILITY LEDs, which indicate the reading reliability during normal reading operation.

2. Set the items for [Options].

When the [Options] button is clicked, the “Special function setting” screen appears.

Set each item.



“Reverse bar code reading”

If “Enable” is checked, the BL-600 Series reads bar codes printed in reverse (white-on-black).

“Decode cancel count”

Do not change from the initial value.

“Quiet zone scale”

Set the minimum value of the quiet zone width to be read with the BL-600 Series. Specify the scale factor of the quiet zone with reference to the narrow bar width (the narrowest bar width in the bar code). Do not change the initial value unless the quiet zone of the target bar code is small.

“Test SW output”

If “Enable” is set, the BL-600 Series sends the read bar code data or the successful reading rate data to the PC while in test mode.

If you do not want to send data while in test mode, remove the check from “Enable”. ⇨ See pages 96 and 98.

* This setting is effective for all reading operations using the TEST switch.

Reference: “Quiet zone” is the margin required on the right and left of a bar code. Normally, it should be 10 or more times wider than the narrow bar width.

4.3 Sending/Receiving Settings

This section describes how to send data to or receive data from the BL-600 Series.

4.3.1 Sending/receiving settings to/from the BL-600 Series

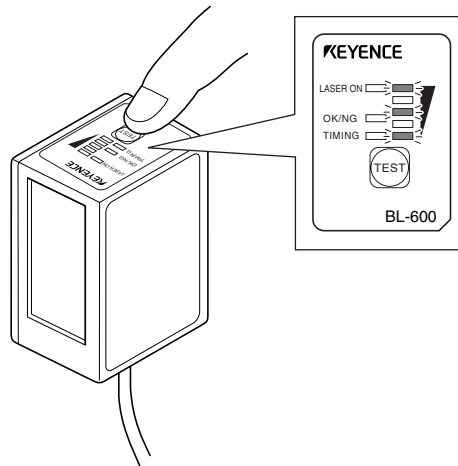
Perform the following procedure to read the settings of the BL-600 Series or to send the updated settings to the BL-600 Series.

* To send/receive settings to/from the BL-600 Series via the BL-V35, refer to the BL-V35 User’s Manual.

1. Connect the BL-600 Series, special power supply unit, and personal computer.
⇨ See “Chapter 3, Connection and Wiring”.

2. Set the BL-600 Series to “setting data send/receive waiting status”.

1) Press the BL-600 TEST switch for 8 seconds.



2) When the 1st, 3rd and 5th STABILITY LEDs from the top flash simultaneously, the communication protocol is temporarily set as indicated below.

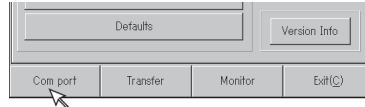
- Baud rate: 9600 bits/s
- Data length: 7 bits
- Parity: Even
- Stop bit length: 1 bit
- PLC link: Disabled
- Multi-drop link: Disabled

Reference: If you know the current communication parameter settings of the BL-600, this step is not necessary. You can send data to the BL-600 by setting the communication parameters of the host computer using [[Com Port]] so that they conform to the current settings of the BL-600.

Note: If PLC link is enabled, you cannot send data to the BL-600 without performing this step because the handshaking protocol is set for PLC link only.

3. Check or change the communication parameter settings of the personal computer.

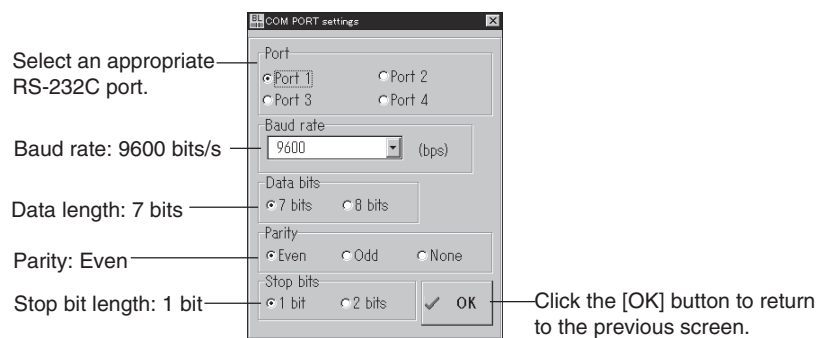
1) Click on **[[Com port]]**.



2) Set each parameter as shown below.

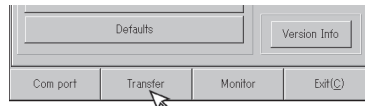
3) Select an appropriate RS-232C port.

4) When the settings are complete, click the **[OK]** button.



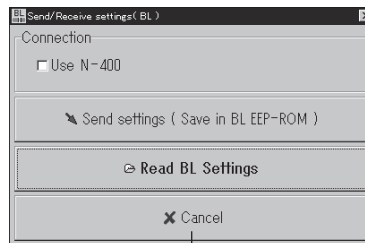
4. Sending/receive settings to/from the BL-600 Series via the N-400.

1) Click on **[[Transfer]]**.



2) The "Send/Receive settings (BL)" screen appears.

- To send the updated settings to the BL-600 Series
Click the **[Send settings]** button.
- To read the settings of the BL-600 Series
Click the **[Read BL settings]** button.



Click the **[Cancel]** button to return to the previous screen.

5. Sending/reading result

The following messages appear to indicate whether the sending/receiving operation was successful or whether it failed.

Sending succeeded



Sending failed



If the operation failed, check the following points:

- Check that the BL-600 Series is in the “setting data send/receive waiting status” during which the 1st, 3rd, and 5th STABILITY LEDs from the top flash simultaneously.
- Check that [[Com port]] is set as shown in (3).
- Check that the special power supply is turned on.
- Check that the RS-232C cable pin assignment of the BL-600 is the same as that of the host computer. ➤ See pages 21, 28 and 35.

Reading succeeded



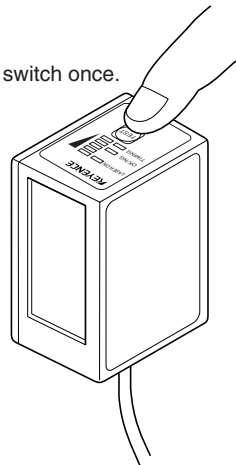
Reading failed



6. Canceling the “setting data send/receive waiting status”.

Press the TEST switch once. The “setting data send/receive waiting status” is canceled.

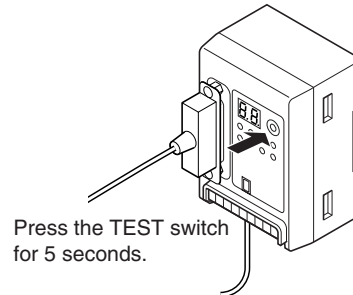
Press the TEST switch once.



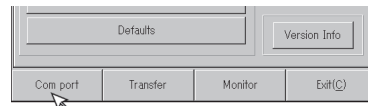
4.3.2 Sending/receiving settings to/from the BL-600 Series via the N-400

Note: It is only possible to send/receive settings with a BL-600 Series that has already established a multi-drop link with the N-400.

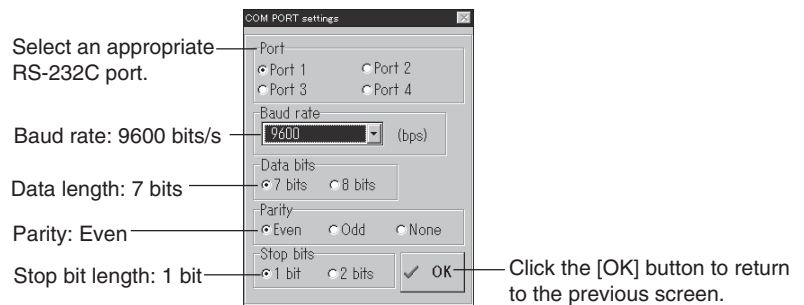
1. Set the N-400 to “setting data send/receive waiting status”.
 - 1) Press the N-400 TEST switch for 5 seconds.



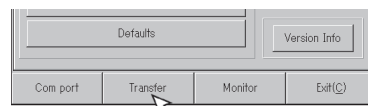
- 2) Communication can begin when “SO (50)” is displayed.
2. Check or change the communication parameter settings of the personal computer.
 - 1) Click on [[Com port]].



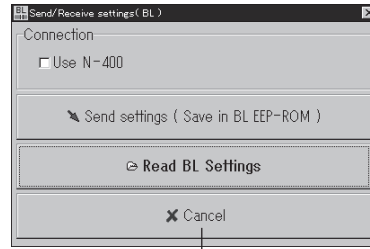
- 2) Set each parameter as shown below.
- 3) Select an appropriate RS-232C port.
- 4) When the settings are complete, click the [OK] button.



3. Sending/receive settings to/from the BL-600 Series via the N-400.
 - 1) Click on [[Transfer]].

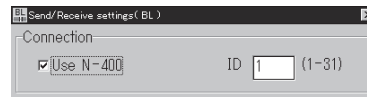


- 2) The “Send/Receive settings (BL)” screen appears.
- To send the updated settings to the BL-600 Series
Select “Use N-400” and enter the ID number of the desired BL-600 Series. Then, click the [Send settings] button.



Click the [Cancel] button to return to the previous screen.

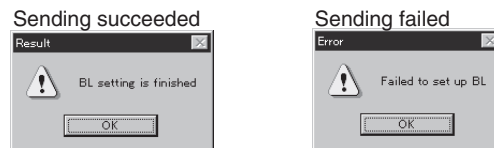
- To read the settings of the BL-600 Series
Select “Use N-400” and enter the ID number of the desired BL-600 Series. Then, click the [Read BL settings] button.



Note: If improper settings are sent to the BL-600 Series, communication with the N-400 is disabled. To avoid problems, read the settings of the BL-600 Series first, then change only the necessary items.

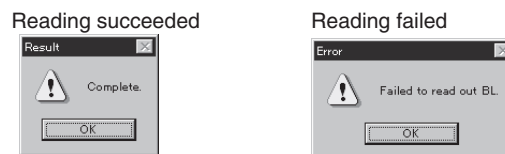
4. Sending/reading result

The following messages appear to indicate whether the sending/receiving operation was successful or whether it failed.



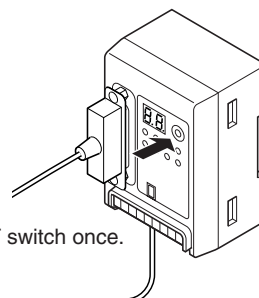
If the operation failed, check the following points:

- Check that the N-400 displays “SO (50)”.
- Check that the settings for the [[Com port]] are specified as described in step 2.
- Check that the N-400 and special power supply unit are turned on.
- Check that the multi-drop link between the N-400 and the BL-600 Series is properly established.



5. Canceling the “communication waiting status”.

Press the TEST switch of the N-400 once. The “communication waiting status” is canceled.



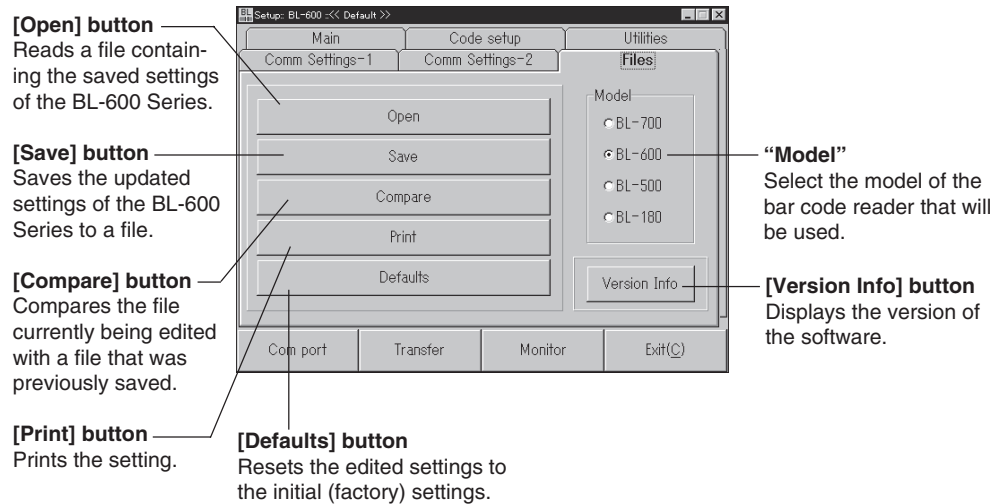
Press the TEST switch once.

4.4 Reading/Saving/Printing File

This section describes how to read, save, or print settings of a file.

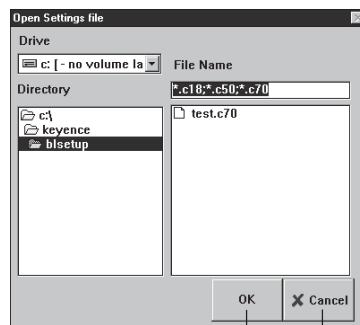
4.4.1 [[Files]] screen

The [[Files]] screen allows the following operation/setting of files (setting data).



4.4.2 Reading a previously saved setting file

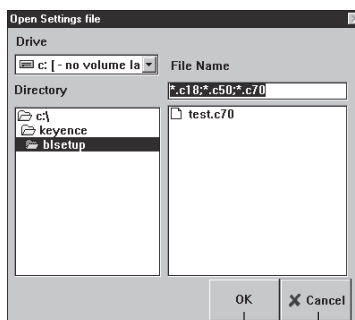
1. Click the [Open] button.
The “Open Settings file” screen appears.
2. Select a file and click the [OK] button.
The saved file is opened.



[OK] button Click [Cancel] to return to the previous screen.

4.4.3 Saving updated settings in a file

1. Click the [Save] button. The “Save Settings file” screen appears.
2. Click in the file name entry field and enter a file name.
Up to 8 characters can be used for a file name.
3. Click the [OK] button.
 - If the entered file name is illegal, an error message appears and the file is not saved.
In this case, click the [OK] button and repeat steps 1 to 3. ↪ See page 67.



[OK] button Click [Cancel] to return to the previous screen.

- If the file is properly saved, the following message appears.



Click the [OK] button to return to the initial screen.

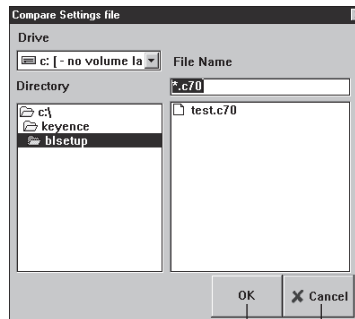
Reference: If a file saved with a name consisting of only alphanumeric (alphabets and numbers) is sent to the BL-600 Series, the file name is also sent. In this case, when you read the settings of the BL-600 Series the next time, you can also read the file name to check the name of the current file of the BL-600 Series. This is convenient for maintenance.

If characters other than alphanumeric are included in a file name, the file name is not sent to the BL-600 Series because the BL-600 Series cannot recognize them.

4.4.4 Comparing the contents of the file currently being edited with a saved file

1. Click the [Compare] button. The “Compare Settings file” screen appears.
2. Select a saved file to be compared and click the [OK] button.

The selected saved file is compared with the file currently being edited.



[OK] button Click [Cancel] to return to the previous screen.

If the settings match

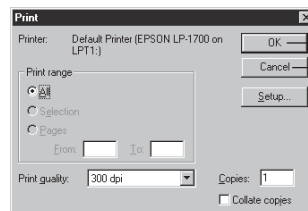


If the settings do not match



4.4.5 Printing contents of a setting file

1. Click the [Print] button. The “Print” screen appears.
2. Specify each item as required.
3. Click the [OK] button to start printing.



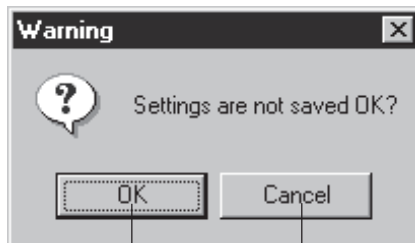
[OK] button
Click [Cancel] to return to the previous screen.

4.4.6 Resetting the edited settings to the initial (factory) settings

1. Click the [Defaults] button.

If you click this button without saving the file currently being edited, a warning message appears.

2. To continue the initialization, click the [OK] button.



[OK] button Click [Cancel] to return to the previous screen.

Note: The [Defaults] button operation is used to initialize the edited settings of the setup software. The settings on the BL-600 Series cannot be initialized.

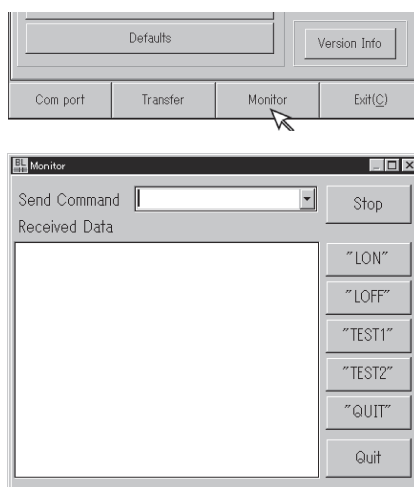
4.5 Using Monitor

This setup software provides the “Monitor” program to check if the BL-600 can send data properly. The “Monitor” program allows you to display the data read by the BL Series on the host computer’s monitor screen, and also to send a command from the host computer to the BL-600 or BL Series.

4.5.1 Receiving data and checking the result

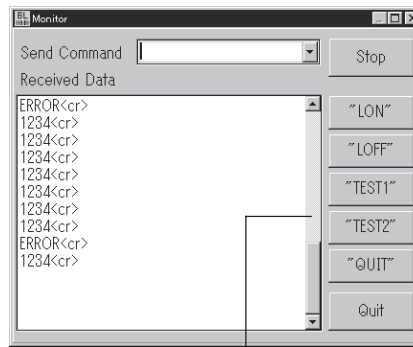
The bar code data read with the BL-600 Series can be received with a personal computer and checked on the screen.

1. Set the communication parameters of the personal computer according to those of the BL-600 Series. ↪ See pages 54 and 55.
2. Click on [[Monitor]]. The MONITOR screen will appear.



3. Receive the bar code data.

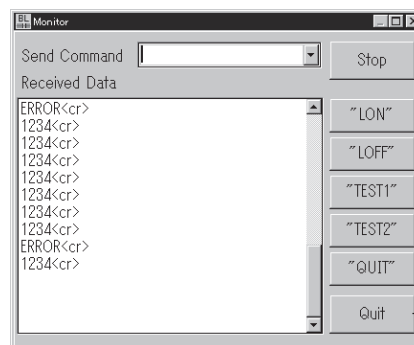
- The bar code data read with the BL-600 Series is displayed on the “Received Data” field.
- You can also see the history of the previous data (up to 1000 lines) using the scroll bar on the right of the “Received Data” field.



Scroll bar

4. Stopping the bar code data display

- 1) Click the [Stop] button. The name of the button changes to [Start] and display of the received data is stopped.

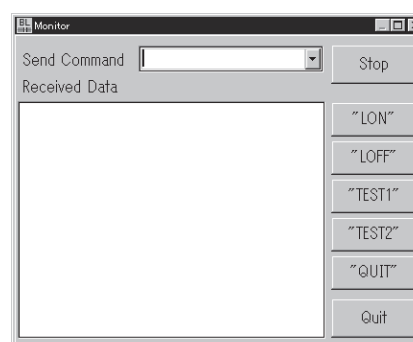
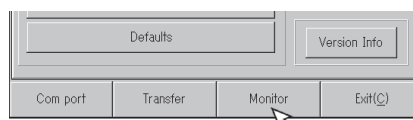


Click [Quit] to return to the previous screen.

- 2) When the [Start] button is clicked, the name of the button changes to [Stop] and display of the received data is restarted.

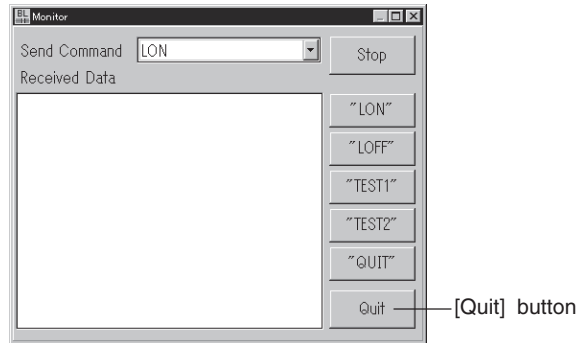
4.5.2 Command transmission ⇨ See pages 114 to 128.

1. Set the communication parameters of the personal computer according to those of the BL-600 Series. ⇨ See pages 54 and 55.
2. Click on [[Monitor]]. The MONITOR screen will appear.



3. Enter the serial communication command in the “Send Command” field (⇨ See pages 114 to 128.) and press the **[ENTER]** key on the keyboard. Now, commands can be sent from a personal computer to the BL-600 Series.

* Use only uppercase characters for the commands.



- Command transmission with the command buttons

Clicking the command buttons on the right side of the screen allows the following commands to be sent to the BL-600 Series.

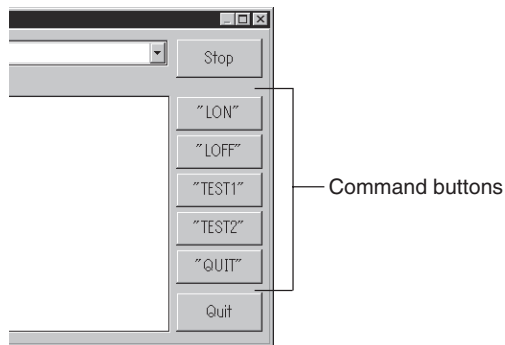
[TEST1] button: Activates the reading rate check mode.

[TEST2] button: Activates the tact check mode.

[QUIT] button: Quits the test mode.

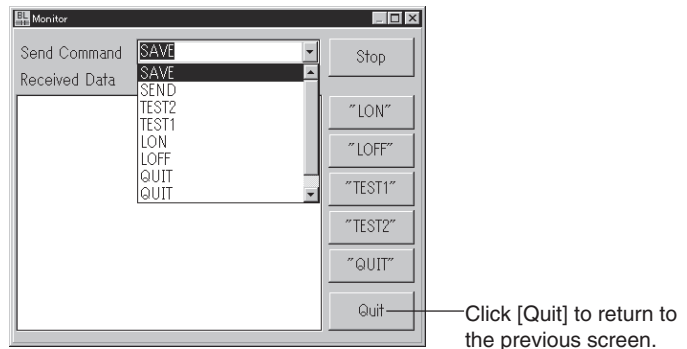
[LON] button: Starts reading.

[LOFF] button: Quits reading.



4. Checking the history of sent commands

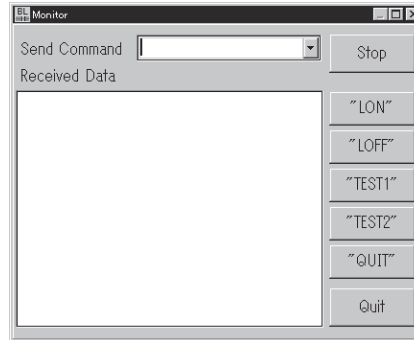
Clicking ▾ of the “Send Command” field displays the history of the sent commands (up to 100 commands).



4.5.3 Starting the test mode

The test mode of the BL-600 Series can be started with a command button.

1. Set the communication parameters of the personal computer according to those of the BL-600 Series. *See pages 54 and 55.*
2. Click on **[Monitor]**. The MONITOR screen will appear.



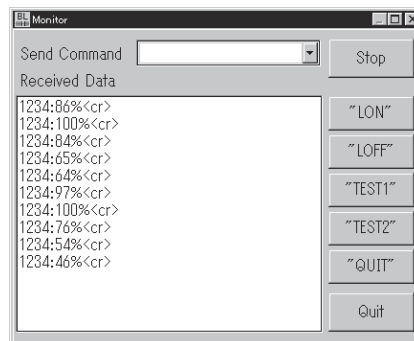
3. Start the test mode by clicking the **[TEST1]** or **[TEST2]** button.

Operation of the BL-600 Series

[TEST1] button: Activates the reading rate check mode.

[TEST2] button: Activates the tact check mode.

- * You can also start the test mode by typing "TEST1" or "TEST2" (uppercase only) in the "Send Command" field and sending it.



4. When the **[QUIT]** button is clicked, test mode is finished.

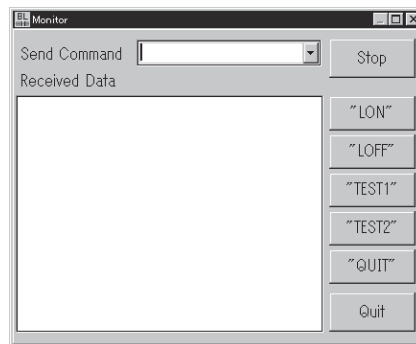
- * You can also end the test mode by typing "QUIT" in the "Send Command" field and sending it.

4.5.4 Changing the scanning width

The scanning width of the BL-600 Series can be changed with a command button.
 ⇨ See page 117.

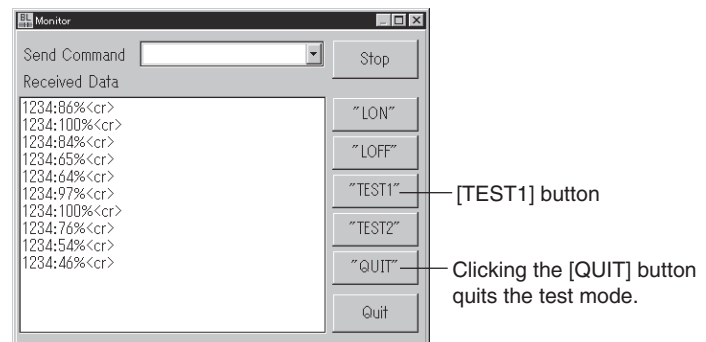
Note: When the scanning width is changed, the laser beam may not be properly applied to the bar codes, resulting in poor readings. Change the scanning width only when it is necessary. Thoroughly check that the change did not affect the reading performance.

1. Set the communication parameters of the personal computer according to those of the BL-600 Series. ⇨ See pages 54 and 55.
2. Click on [[Monitor]]. The MONITOR screen will appear.



3. Click the [TEST1] button.

The BL-600 Series enters test mode and emits a laser beam.



4. Specify the starting angle of scanning.

Send the following command.

SDEG a [ENTER] [a: 0 to 400 (Unit: 0.1°)]
 ↑ [*Initial value = 0]
 Input from the keyboard

- * Specify an appropriate angle by checking the field of the laser beam.

5. Specify the scanning angle.

Send the following command.

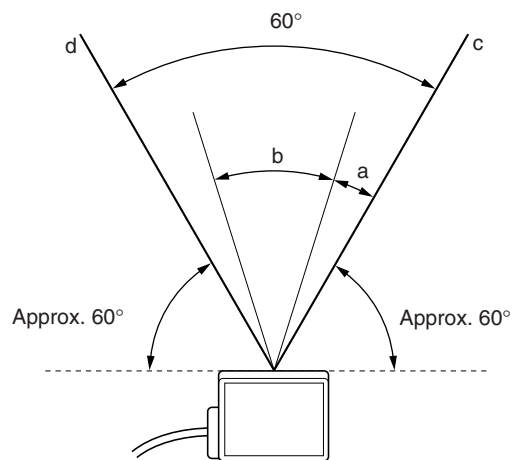
WDEG b [ENTER] [b: 400 to 600 (Unit: 0.1°)]
 ↑ [*Initial value = 600]
 Input from the keyboard

- * Specify an appropriate angle by checking the field of the laser beam.

6. When the setting is complete, quit the test mode.

Click the [QUIT] button.

- * The changed scanning width is retained even after the BL-600 Series is turned off.



Note 1: The scanning width cannot be specified to exceed the angle range between “c” and “d” (60°).

Note 2: The angle specified in the steps above should be used as a guide. If a precise setting is required, adjust the position of each bar code reader separately after installation.

4.6 List of Error Messages

	Error message	Contents
Errors during setup	“Entered data is incorrect. [OK]”	The entered data is incorrect. Re-enter the correct data.
Errors during communication	“Communication with BL-600 failed. [OK]”	Error during communication with the BL-600 (for sending settings). ⇨ See page 56.
	“Readout from BL-600 failed. [OK]”	Error during communication with the BL-600 (for reading settings). ⇨ See page 56.
	“The specified model is incorrect. [OK]”	The model set in the setup software is not the same as the model that is connected. ⇨ See page 42.
Errors file editing	“Accessing file during rejected. [OK]”	No floppy disk is inserted. The floppy disk is write-protected. The floppy disk is full.
	“File not found. [OK]”	The file name is incorrect. Enter a correct file name. ⇨ See page 60.
	“File name incorrect. [OK]”	

4.7 Example of Printing from the Setup Software

When "Print" is executed from the setup software, the following data is printed.

```
/// New setting data [Untitled] ///
```

```
< < Model = BL-600 > >
```

```
[x] Selected  
[ ] -----  
=> Changed
```

1) Main

```
[Read mode] [x] Single [ ] Multi 1 [ ] Multi 2 [ ] Multi 3  
[Data-send] [x] After read [ ] At trigger input  
[Repeat-reading time] [10] x 100 ms  
[Decoding match count] [2] times  
[Read error] ERROR [4552524F52]  
[Add Decoding match count] [ ] Enable  
[Add scan count] [ ] Enable  
[Add code type] [ ] Enable  
[Add label orientation] [ ] Enable  
[Add symbology ID.] [ ] Enable  
[Add PMI.] [ ] Enable
```

2) Trigger setup

```
[Signal type] [x] Level [ ] One shot  
[One shot input time] [10] x 100 ms  
[Input time] [x] 2 ms [ ] 10 ms  
[State] [x] Normally open [ ] Normally close  
[Command for Trigger ON] LON [4C4F4E]  
[Command for Trigger OFF] LOFF [4C4F4646]  
[Test mode initiated with input ON] [x] OFF [ ] Reading-rate check [ ] Tact check  
[Test mode initiated upon power-up] [x] OFF [ ] Reading-rate check [ ] Tact check  
[Power-on trigger] [ ] Enable
```

3) Comm Settings-1

```
[Baud rate] 9600 bps.  
[data bits] [x] 7 bits [ ] 8 bits  
[Parity] [x] Even [ ] Odd [ ] None  
[Stop bits] [x] 1 bit [ ] 2 bits  
[RTS/CTS] [ ] Use RTS/CTS handshaking  
[Multi-drop link(RS-485)] [ ] Enable  
[ID number] No. [1]
```

4) Comm Settings-2

```
[Use PLC] [ ] Enable  
[Handshaking] [x] None [ ] PASS/RTRY [ ] ACK/NAK  
[Header] [x] None [ ] STX [ ] ESC [ ] Custom  
[Delimiter] [x] CR [ ] CR+LF [ ] ETX [ ] Custom  
[Partition mark] : [3A]  
[Intermediate delimiter] , [2C]  
[Checksum] [ ] Enable  
[Send delay time] [0] ms
```

5) Utility

```
[Stability LED] [ ] Use stability LED  
[OK/NG output duration] [50] x 10 ms  
[Preset data] = [no data]  
[Reverse bar code reading] [ ] Enable  
[Quiet zone scale] [7] Times  
[Decode cancel count] [0]  
[Test SW output] [x] Enable
```

(1/2)

[Code 1 setup] Bar code = CODE39

[Max code length]	[32]
[Min code length]	[3]
[Send start/stop character (*)]	<input type="checkbox"/> Enable
[Inspect check-digit [Modulus 43]]	<input type="checkbox"/> Enable
[Send check-digit]	<input checked="" type="checkbox"/> Enable
-----Options setup-----	
[Max code length output]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse
[Effective]	[32]
[Starting]	[1]
[Specify label orientation]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse

[Code 2 setup] Bar code = Codabar

[Max code length]	[32]
[Min code length]	[3]
[Start/stop character]	<input type="checkbox"/> Do not send <input checked="" type="checkbox"/> Lower-case <input type="checkbox"/> Upper-case
[Inspect check-digit]	<input type="checkbox"/> Enable
[Send check-digit]	<input checked="" type="checkbox"/> Enable
[Type of check-digit]	Modulus 16
-----Options setup-----	
[Max code length output]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse
[Effective]	[32]
[Starting]	[1]
[Specify label orientation]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse

[Code 3 setup] Bar code = UPC/EAN

[Read EAN 13(UPC-A)]	<input checked="" type="checkbox"/> Enable
[Read EAN 8]	<input checked="" type="checkbox"/> Enable
[Read UPC-E]	<input checked="" type="checkbox"/> Enable
[No. of UPC-A output]	<input checked="" type="checkbox"/> 13 digits <input type="checkbox"/> 12 digits
[Add UPC-E system code 0]	<input checked="" type="checkbox"/> Do not add <input type="checkbox"/> Add
-----Options setup-----	
[Max code length output]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse
[Effective]	[32]
[Starting]	[1]
[Specify label orientation]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse

[Code 4 setup] Bar code = CODE128

[Max code length]	[32]
[Min code length]	[1]
[EAN-128 support]	<input type="checkbox"/> Enable
-----Options setup-----	
[Max code length output]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse
[Effective]	[32]
[Starting]	[1]
[Specify label orientation]	<input checked="" type="checkbox"/> Not used <input type="checkbox"/> Forward <input type="checkbox"/> Reverse

Printed: 99/08/07 20:40:28

(2/2)

